# Lower box dimension of infinitely generated self-conformal sets 

Amlan Banaji \& Alex Rutar

AbStract. Let $\Lambda$ be the limit set of an infinite conformal iterated function system and let $F$ denote the set of fixed points of the maps. We prove that the box dimension of $\Lambda$ exists if and only if

$$
\overline{\operatorname{dim}}_{\mathrm{B}} F \leq \max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \underline{\operatorname{dim}}_{\mathrm{B}} F\right\} .
$$

In particular, this provides the first examples of sets of continued fraction expansions with restricted digits for which the box dimension does not exist.

More generally, we establish an explicit asymptotic formula for the covering numbers $N_{r}(\Lambda)$ in terms of $\operatorname{dim}_{\mathrm{H}} \Lambda$ and the covering function $r \mapsto N_{r}(F)$, where $N_{r}(\cdot)$ denotes the least number of open balls of radius $r$ required to cover a given set. Such finer scaling information is necessary: in general, the lower box dimension $\underline{\operatorname{dim}}_{B} \Lambda$ is not a function of the Hausdorff dimension of $\Lambda$ and the upper and lower box dimensions of $F$, and we prove sharp bounds for $\operatorname{dim}_{B} \Lambda$ in terms of these three quantities.

Key words and phrases. lower box dimension, infinite iterated function system, continued fractions

2020 Mathematics Subject Classification. 28A80 (Primary); 37C45, 37B10, 11K50 (Secondary)

## Contents

1 Introduction ..... 2
1.1 Dynamical invariance and box dimension ..... 2
1.2 Countably generated self-conformal sets ..... 4
1.3 Formula for the lower box dimensions ..... 6
1.4 Reformulation in terms of growth rates of covering numbers ..... 8
1.5 Further research ..... 10
1.6 Notation, conventions, and structure of paper ..... 10
2 An asymptotic formula for covering numbers ..... 10
2.1 Bounded neighbourhood condition ..... 11
2.2 Regularity of covering numbers ..... 11
2.3 Properties of the lower box dimension formula ..... 13
2.4 Proof of the asymptotic formula ..... 15
3 Consequences of the asymptotic formula ..... 20
3.1 Classifying existence of the box dimension ..... 20
3.2 Some preliminaries on the covering class ..... 22
3.3 An alternative asymptotic formula ..... 25
4 Examples and applications ..... 27
4.1 Constructing countable discrete sets ..... 27
4.2 Continued fraction expansions with restricted entries ..... 31
Acknowledgements ..... 32
References ..... 32

## 1. INTRODUCTION

1.1. Dynamical invariance and box dimension. One of the fundamental aspects of the study of dynamical systems is the structure of invariant sets. More precisely, suppose $X$ is a set and $f: X \rightarrow X$ is a function. We say that a set $\Lambda \subset X$ is invariant if $f(\Lambda)=\Lambda$. Invariant sets for dynamical systems, particularly when the dynamics are expanding or chaotic, often have highly intricate local structure. As a result, a standard lens through which to view the geometry of invariant sets is that given by dimension theory. The dimension theory of dynamical systems has its origins in the seminal work of Bowen [Bow79] on quasicircles and Ruelle [Rue82] on conformal repellers. It has since developed into a substantial field in its own right. For an overview, see, for instance, the monographs [Bar08; Pes98], surveys [BG11; Sch01], and notable recent progress [BHR19; CPZ19; DS17; Jur23].

Of the notions of fractal dimension, one of the most familiar, and perhaps the simplest to define, is the box dimension, also known as Minkowski dimension. More precisely, the lower and upper box dimensions of a non-empty bounded set $E \subset \mathbb{R}^{d}$ are defined respectively as

$$
\underline{\operatorname{dim}}_{\mathrm{B}} E=\liminf _{r \rightarrow 0} \frac{\log N_{r}(E)}{\log (1 / r)}, \quad \overline{\operatorname{dim}}_{\mathrm{B}} E=\limsup _{r \rightarrow 0} \frac{\log N_{r}(E)}{\log (1 / r)}
$$

where $N_{r}(E)$ denotes the least number of open balls of radius $r$ required to cover $E$. If these two notions coincide, we call the common value the box dimension of $E$ and denote it by $\operatorname{dim}_{\mathrm{B}} E$. If the box dimension does not exist, this indicates that the extent to which the set $E$ 'fills up space' varies substantially at different scales.

It is well known that for general sets $E$, the inequalities $\operatorname{dim}_{\mathrm{H}} E \leq \operatorname{dim}_{\mathrm{B}} E \leq$ $\operatorname{dim}_{\mathrm{B}} E$ always hold and moreover can be strict, where $\operatorname{dim}_{\mathrm{H}} E$ denotes the Hausdorff dimension of $E$. On the other hand, if $E$ is invariant for a map $f$ which is uniformly expanding on $E$, then in many cases these will be equalities. A core question in the dimension theory of dynamical systems, and the question motivating this paper, is the following.

Question 1.1. For which sets that are invariant for an expanding dynamical system does the box dimension exist?

It was proved independently in [Bar96; GP97] (generalising a result in [Fa189]) that if $E$ is a compact subset of a Riemannian manifold which is invariant under a smooth conformal map $f$ that is uniformly expanding on $E$, then $\operatorname{dim}_{\mathrm{H}} E=$ $\underline{\operatorname{dim}}_{\mathrm{B}} E=\overline{\operatorname{dim}}_{\mathrm{B}} E$. Moreover, if $E$ is a self-similar or self-conformal set (these are the most familiar classes of fractal sets), then $\operatorname{dim}_{\mathrm{H}} E=\underline{\operatorname{dim}}_{\mathrm{B}} E=\overline{\operatorname{dim}}_{\mathrm{B}} E$.

The assumption that the dynamics are conformal (meaning that the differential $f_{x}^{\prime}$ is a scalar multiple of a similarity map at each $x \in E$ ), and the assumption that the invariant set $E$ is compact, are important. It has been known that a gap between Hausdorff and lower box dimension is possible if $f$ is non-conformal since the work of Bedford [Bed84] and McMullen [McM84] in 1984 (the invariant sets are self-affine Bedford-McMullen carpets). The box and Hausdorff dimension can also differ for Julia sets of certain non-rational hyperbolic functions [Sta01; Sta04]. Moreover, from work of Mauldin \& Urbański [MU96; MU99] in the 1990s one can see that there are non-compact sets which are invariant for a dynamical system given by a function which extends to a smooth expanding conformal map, and whose Hausdorff and box dimensions differ. In the latter case, the invariant set is an infinitely generated self-conformal set; such sets are described in detail below.

On the other hand, there has been much less progress on establishing a gap between lower and upper box dimension (i.e. non-existence of box dimension). In the non-conformal setting, it is a major problem to determine whether the box dimension of every self-affine set exists, and while this is known to be true in many cases [BHR19; Bed84; Fal88; McM84], the general problem remains open. The usual examples of sets whose box dimension may not exist, such as certain sequences, Cantor-like sets [Fal14, §2], and inhomogeneous attractors [Fra12], are not dynamically invariant. The only non-existence result for dynamically invariant sets of which we are aware is due to Jurga [Jur23], who recently showed that there exists a compact subset of the torus which is invariant under a smooth expanding toral endomorphism and whose box dimension does not exist. Crucial to Jurga's example is the two-dimensional nature of the torus and the non-conformal nature of the dynamics.

In this paper, we give the first examples (as far as we are aware) of non-compact sets whose box dimension does not exist and which are invariant for a dynamical system given by a function which extends to a smooth uniformly expanding conformal map. This is the case even for a particularly old and well-studied conformal map: the Gauss map $g:(0,1] \rightarrow S^{1}$ given by $g(x)=1 / x$, where $S^{1}$ denotes the circle $\mathbb{R} / \mathbb{Z}$. Canonical examples of invariant sets for the Gauss map are the numbers with continued fraction expansions having digits restricted to a given subset of $\mathbb{N}$. This is also the case for the set $\Lambda$ in the theorem below.

Theorem A. There exists a Borel set $\Lambda \subset(0,1)$ which is invariant under the Gauss map and whose box dimension does not exist.

Theorem A is in fact a consequence of our study of infinitely generated selfconformal sets in this paper. Such sets were first introduced in [MU96], and as mentioned above, motivating examples of infinitely generated self-conformal sets are real or complex numbers whose continued fraction expansions are restricted
to a given countable set [MU99]. Infinitely generated self-conformal sets are particularly well-studied in the literature; for a certainly incomplete selection, see for instance [BF23; BF24; CLU20; PU21; SW15; WW08] and [Fra20, Section 9.2] and more references therein. Infinite systems are also useful in the presence of non-uniformly expanding dynamics or parabolicity, since one can often associate with such a system an 'induced' infinite but uniformly expanding system [MU02; MU00]. Furthermore, infinite systems have been used to calculate dimensions of sets which are important in complex dynamics [MU22]. While the Hausdorff and upper box dimensions of infinitely generated self-conformal sets are wellunderstood [MU96; MU99], despite over two decades since the original results, much less is known concerning the lower box dimension.

In this paper we remedy this gap by providing a precise formula for the lower box dimension of such sets; this formula is substantially more complicated than the one for upper box dimension. Moreover, we characterise when the lower and upper box dimensions of such sets coincide.
1.2. Countably generated self-conformal sets. In order to state our main result precisely, we introduce our main objects under consideration: countable conformal iterated function systems.

Following [MU96], let $X$ be a compact connected subset of $\mathbb{R}^{d}$ with the Euclidean norm and let $\mathcal{I}$ be a countable index set. Fix a family of injective uniformly contracting maps $S_{i}: X \rightarrow X$ for $i \in \mathcal{I}$ : that is, there is a constant $0<c<1$ so that for all $x, y \in X$ and $i \in \mathcal{I}$,

$$
0<\left\|S_{i}(x)-S_{i}(y)\right\| \leq c \cdot\left\|S_{i}(x)-S_{i}(y)\right\|
$$

We use symbolic notation on the set $\mathcal{I}^{*}$ of finite sequences on $\mathcal{I}$, equipped with the operation of concatenation. Given $\gamma=\left(i_{1}, i_{2}, \ldots\right) \in \mathcal{I}^{\mathbb{N}}$ and $n \in \mathbb{N}$, we write $\left.\gamma\right|_{n}:=\left(i_{1}, \ldots, i_{n}\right) \in \mathcal{I}^{n}$. For $n \in \mathbb{N} \cup\{0\}$ and $\mathrm{i}=\left(i_{1}, \ldots, i_{n}\right) \in \mathcal{I}^{n}$, we write

$$
S_{\mathrm{i}}=S_{i_{1}} \circ \cdots \circ S_{i_{n}} .
$$

Then, associated with the IFS $\left\{S_{i}\right\}_{i \in \mathcal{I}}$ is the limit set (also called the attractor):

$$
\Lambda:=\bigcup_{\gamma \in \mathcal{I}^{\mathbb{N}}} \bigcap_{n=1}^{\infty} S_{\gamma 1_{n}}(X)
$$

Equivalently, $\Lambda$ is the largest subset of $X$ (by inclusion) satisfying the invariance relationship

$$
\Lambda=\bigcup_{i \in \mathcal{I}} S_{i}(\Lambda)
$$

Note that $\Lambda$ is not in general a compact set. On the other hand, if for each $x \in X$ there are only finitely many indices $i$ such that $x \in S_{i}(X)$ (which is the case for all systems which we will consider in this paper), then $\Lambda$ is an $F_{\sigma \delta}$ subset of $X$.

Throughout, $\Lambda$ will denote the limit set and $F$ will denote the (countable) set of fixed points of the contractions $\left\{S_{i}\right\}_{i \in \mathcal{I}}$. (Some discussion concerning the choice of $F$ can be found in $\S 2.3$.)

Definition 1.2. We say that the IFS $\left\{S_{i}\right\}_{i \in \mathcal{I}}$ is conformal if the following additional properties are satisfied:
(i) Conformality: There exists an open, bounded, connected subset $V \subset \mathbb{R}^{d}$ such that $X \subset V$ and such that for each $i \in \mathcal{I}, S_{i}$ extends to a conformal $C^{1+\varepsilon}$ diffeomorphism on $V$.
(ii) Bounded distortion: There exists $K \geq 1$ such that $\left\|S_{\mathbf{i}}^{\prime}(x)\right\| \leq K\left\|S_{\mathbf{i}}^{\prime}(y)\right\|$ for all $x, y \in V$ and $\mathrm{i} \in \mathcal{I}^{*}$. Here, $S_{\mathrm{i}}^{\prime}(x)$ denotes the Jacobian of the map $S_{\mathrm{i}}$ at $x$ and $\|\cdot\|$ denotes the spectral matrix norm.

In light of the uniformly contracting property, if we define

$$
\rho(\mathrm{i})=\sup _{x \in X}\left\|S_{\mathrm{i}}^{\prime}(x)\right\| \quad \text { for } \quad \mathrm{i} \in \mathcal{I}^{*},
$$

then $\xi:=\sup _{i \in \mathcal{I}} \rho(i)<1$. Moreover, by the chain rule, sub-multiplicativity of the matrix norm, and the bounded distortion property, for any $i, j \in \mathcal{I}^{*}$,

$$
\begin{equation*}
K^{-1} \rho(\mathrm{i}) \rho(\mathrm{j}) \leq \rho(\mathrm{ij}) \leq \rho(\mathrm{i}) \rho(\mathrm{j}) . \tag{1.1}
\end{equation*}
$$

We also require some standard separation conditions; see, for instance, [MU96].
(iii) Open set condition: The set $X$ has non-empty topological interior $U$, and $S_{i}(U) \subset U$ for all $i \in \mathcal{I}$ and $S_{i}(U) \cap S_{j}(U)=\varnothing$ for all $i, j \in \mathcal{I}$ with $i \neq j$.
(iv) Cone condition: $\inf _{x \in X} \inf _{r \in(0,1)} r^{-d} \mathcal{L}^{d}(B(x, r) \cap U)>0$.

See $\S 2.1$ for more discussion concerning separation conditions.
Throughout this paper, we will assume that $\left\{S_{i}\right\}_{i \in \mathcal{I}}$ is a conformal IFS satisfying the open set condition and the cone condition. We will refer to such a system in shorthand as a CIFS.

In order to study the dimension theory of the limit set $\Lambda$ of a CIFS, Mauldin \& Urbański [MU96] defined the topological pressure $P:(0, \infty) \rightarrow[-\infty, \infty]$ by

$$
\begin{equation*}
P(t):=\lim _{n \rightarrow \infty} \frac{1}{n} \log \sum_{\mathrm{i} \in \mathcal{I}^{n}} \rho(\mathrm{i})^{t} . \tag{1.2}
\end{equation*}
$$

The limit necessarily exists by a sub-additivity argument using (1.1). In the same paper, they established a formula for the Hausdorff dimension of the limit set in terms of the pressure:

$$
\begin{equation*}
\operatorname{dim}_{\mathrm{H}} \Lambda=\inf \{t \geq 0: P(t)<0\} \tag{1.3}
\end{equation*}
$$

We also know from [MU99] that the upper box and packing dimensions coincide and are given by

$$
\overline{\operatorname{dim}}_{\mathrm{B}} \Lambda=\operatorname{dim}_{\mathrm{P}} \Lambda=\max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \overline{\operatorname{dim}}_{\mathrm{B}} F\right\},
$$

see [BF23; MU99]. Other notions of dimension, such as the upper intermediate dimensions [BF23] and Assouad-type dimensions [BF24], have also been studied.
1.3. Formula for the lower box dimensions. The lower box dimension of general sets has some interesting properties not shared by Hausdorff or upper box dimension. For instance, the lower box dimension need not be finitely stable: it is not too challenging to construct sets $E_{1}, E_{2}$ such that $\operatorname{dim}_{\mathrm{B}}\left(E_{1} \cup E_{2}\right)>$ $\max \left\{\underline{\operatorname{dim}}_{\mathrm{B}} E_{1}, \underline{\operatorname{dim}}_{\mathrm{B}} E_{2}\right\}$ by choosing the scales at which each set is "large" to be very different. As we will see, this sensitivity of the lower box dimension to the finer scaling properties of the underlying set leads to much more interesting behaviour for the limit set of a CIFS than appears for the upper box dimension.

For the limit set of a CIFS, the following bounds for lower box dimension are immediate from the work of Mauldin \& Urbański:

$$
\begin{equation*}
\max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \underline{\operatorname{dim}}_{\mathrm{B}} F\right\} \leq \underline{\operatorname{dim}}_{\mathrm{B}} \Lambda \leq \overline{\operatorname{dim}}_{\mathrm{B}} \Lambda=\max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \overline{\operatorname{dim}}_{\mathrm{B}} F\right\} . \tag{1.4}
\end{equation*}
$$

In general, the lower bound in (1.4) is sharp in a sense which will become clear below. In contrast, it turns out the upper bound is not sharp in general. In fact, our main result provides a precise classification of the existence of the box dimension of $\Lambda$ which equivalently states that the box dimension of $\Lambda$ exists if and only if the bounds in (1.4) coincide.
Theorem B. Let $\Lambda$ be the limit set of a CIFS. Then $\operatorname{dim}_{B} \Lambda=\overline{\operatorname{dim}}_{B} \Lambda$ if and only if

$$
\overline{\operatorname{dim}}_{\mathrm{B}} F \leq \max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \underline{\operatorname{dim}}_{\mathrm{B}} F\right\} .
$$

In particular, non-existence of the box dimension is common.
Theorem B will follow from an explicit asymptotic formula for $N_{r}(\Lambda)$ in terms of the scaling function $r \mapsto N_{r}(F)$ and the Hausdorff dimension of the limit set $\Lambda$, which we now state.

Given the set of fixed points $F$ and $r \in(0,1)$, we define the box dimension estimate at scale $r$ by

$$
s(r):=\frac{\log N_{r}(F)}{\log (1 / r)} .
$$

For $0<r<1$ and $0<\theta \leq 1$, we define

$$
\begin{equation*}
\Psi(r, \theta):=(1-\theta) \operatorname{dim}_{\mathrm{H}} \Lambda+\theta s\left(r^{\theta}\right) \tag{1.5}
\end{equation*}
$$

and set $\Psi(r, 0):=\lim _{\theta \rightarrow 0} \Psi(r, \theta)$. We then set

$$
\psi(r):=\max _{\theta \in[0,1]} \Psi(r, \theta) ;
$$

the maximum exists by upper semi-continuity of the $\operatorname{map} \theta \mapsto N_{r^{\theta}}(F)$. A depiction of the function $\psi(r)$ in terms of the box dimension estimate $s(r)$ can be found in Figure 1.
Theorem C. Let $\Lambda$ be the limit set of a CIFS on $\mathbb{R}^{d}$ with fixed points $F$ and function $\psi$ as above. Then

$$
\lim _{r \rightarrow 0}\left(\frac{\log N_{r}(\Lambda)}{\log (1 / r)}-\psi(r)\right)=0
$$



Figure 1. A plot of the functions $s(r)$ (dashed), the function $\psi$ (solid), and $\operatorname{dim}_{H} \Lambda$ (dotted). The domain has been transformed by the orderreversing map $x=\log \log (1 / r)$-see Proposition 1.5 for more detail.

In particular,

$$
\underline{\operatorname{dim}}_{\mathrm{B}} \Lambda=\liminf _{r \rightarrow 0} \psi(r) .
$$

We now make several comments on this result.

1. The formula only depends on the contraction ratios through the Hausdorff dimension. On the other hand, it very much depends on the scaling properties of the set of fixed points.
2. The formula can depend on the Hausdorff dimension even when $\operatorname{dim}_{H} \Lambda<$ $\operatorname{dim}_{\mathrm{B}} F$.
3. Heuristically, the formula says that $N_{r}(\Lambda) \geq N_{r}(F)$ should be as small as possible while still being at least $\operatorname{dim}_{\mathrm{H}} \Lambda$-dimensional between all pairs of scales. This heuristic can be made precise; the details can be found in $\S 1.4$. In some sense, this is a more quantitative version of the observation that $\Lambda$ contains Ahlfors-David $\lambda$-regular subsets for all $\lambda<\operatorname{dim}_{H} \Lambda$.
4. Since $\lim _{r \rightarrow 0} \Psi(r, 0)=\operatorname{dim}_{H} \Lambda$ and $\liminf _{r \rightarrow 0} \Psi(r, 1)=\underline{\operatorname{dim}_{B} F \text {, the trivial }}$ bound

$$
\underline{\operatorname{dim}}_{\mathrm{B}} \Lambda=\liminf _{r \rightarrow 0} \psi(r) \geq \max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \underline{\operatorname{dim}}_{\mathrm{B}} F\right\}
$$

corresponds to the endpoints of the estimate $\psi(r)$.
5. A straightforward argument using only the definition of the upper box dimension gives that

$$
\overline{\operatorname{dim}}_{\mathrm{B}} \Lambda=\limsup _{r \rightarrow 0} \psi(r)=\max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \overline{\operatorname{dim}}_{\mathrm{B}} F\right\} .
$$

See the proof of Lemma 2.3 for more detail. In particular, we recover the known results for the upper box dimension from [MU99].
As an application of Theorem C, we obtain the following bounds only assuming coarse scaling properties of $F$. Given $0 \leq s \leq t \leq \alpha$ and $0 \leq h \leq \alpha$, define the
compact interval

$$
\mathcal{D}(h, s, t, \alpha)= \begin{cases}\{h\} & : t \leq h, \\ {\left[\max \{h, s\}, h+\frac{(t-h)(\alpha-h) s}{\alpha \cdot t-h \cdot s}\right]} & : t>h .\end{cases}
$$

Observe that $\mathcal{D}(h, s, t, \alpha)$ is a not a singleton if and only if $0<h<t$ and $0<s<t$. We then have the following result.

Theorem D. Let $\Lambda$ be the limit set of a CIFS on $\mathbb{R}^{d}$. Then

$$
\underline{\operatorname{dim}}_{\mathrm{B}} \Lambda \in \mathcal{D}\left(\operatorname{dim}_{\mathrm{H}} \Lambda, \underline{\operatorname{dim}}_{\mathrm{B}} F, \overline{\operatorname{dim}}_{\mathrm{B}} F, d\right) .
$$

Moreover, these bounds are sharp in the following sense: for any $0<h<d, 0 \leq s \leq t \leq d$, and

$$
\beta \in \mathcal{D}(h, s, t, d)
$$

there is a CIFS of similarity maps on $\mathbb{R}^{d}$ with limit set $\Lambda$ and fixed points $F$ such that $\operatorname{dim}_{\mathrm{H}} \Lambda=h, \underline{\operatorname{dim}}_{\mathrm{B}} F=s, \operatorname{dim}_{\mathrm{B}} F=t$, and $\underline{\operatorname{dim}}_{\mathrm{B}} \Lambda=\beta$.

In particular, we see that the inequalities $\operatorname{dim}_{\mathrm{H}} \Lambda \leq \operatorname{dim}_{\mathrm{B}} \Lambda \leq \operatorname{dim}_{\mathrm{B}} \Lambda$ can be strict or non-strict in any combination. This is in stark contrast to the case of finitely generated self-conformal sets, whose Hausdorff and upper box dimensions are always equal.
Remark 1.3. The family of sets $\mathcal{D}(h, s, t, \alpha)$ is monotonically increasing in $\alpha$ for fixed $h, s, t$. Moreover,

$$
\begin{aligned}
\mathcal{D}(h, s, t, \infty) & :=\lim _{\alpha \rightarrow \infty} \mathcal{D}(h, s, t, \alpha) \\
& = \begin{cases}\{h\} & : t \leq h, \\
{\left[\max \{h, s\}, s+\left(1-\frac{s}{t}\right) h\right]} & : t>h .\end{cases}
\end{aligned}
$$

This gives non-trivial bounds which are valid in all dimensions simultaneously. The right endpoint of $\mathcal{D}(h, s, t, \infty)$ is always at most $\max \{h, t\}$, and is equal to this upper bound if and only if the box dimension of $\Lambda$ exists.
1.4. Reformulation in terms of growth rates of covering numbers. To conclude, given a CIFS with limit set $\Lambda$, we recast our asymptotic formula for $N_{r}(\Lambda)$ in terms of a certain minimal growth rate of covering numbers. The purpose of this is to make rigorous the claim following the statement of Theorem C that $N_{r}(\Lambda) \geq N_{r}(F)$ is as small as possible while being at least $\operatorname{dim}_{H} \Lambda$-dimensional between all pairs of scales.

Let $d \in \mathbb{N}$ and fix a non-empty bounded subset $E \subset \mathbb{R}^{d}$. Then for $0<r<1$, define

$$
s_{E}(r):=\frac{\log N_{r}(E)}{\log (1 / r)} .
$$

Definition 1.4. Let $0 \leq \lambda \leq \alpha$ be arbitrary. Let $\mathcal{G}(\lambda, \alpha)$ denote the set of continuous functions $g: \mathbb{R} \rightarrow[\lambda, \alpha]$ such that

$$
D^{+} g(x) \in[\lambda-g(x), \alpha-g(x)]
$$

where

$$
D^{+} g(x):=\limsup _{\varepsilon \rightarrow 0^{+}} \frac{g(x+\varepsilon)-g(x)}{\varepsilon}
$$

is the upper right Dini derivative of $g$ at $x$.
We say that two functions $f, g: \mathbb{R} \rightarrow \mathbb{R}$ are asymptotically equivalent, and write $f \sim g$, if

$$
\lim _{x \rightarrow \infty}(f(x)-g(x))=0
$$

It is clear that $\sim$ is an equivalence relation.
The point here is that for a non-empty bounded set $E \subset \mathbb{R}^{d}$, after a change of domain, the function $s_{E}$ is asymptotically equivalent to a member of $\mathcal{G}(0, d)$. This observation was essentially made in [BR22], and is made precise in the following proposition.
Proposition 1.5. Let $E \subset \mathbb{R}^{d}$ be non-empty and bounded with associated function $f: \mathbb{R} \rightarrow \mathbb{R}$ defined by

$$
f(x)=s_{E}(\exp (-\exp (x)))
$$

Then there exists $g \in \mathcal{G}(0, d)$ such that $f \sim g$.
The proof is straightforward though requires a slight amount of attention. It follows from a slightly stronger version stated in Proposition 3.5.

With Proposition 1.5 in mind, we make the following definition.
Definition 1.6. Let $E \subset \mathbb{R}^{d}$ be non-empty and bounded. We say that $E$ has covering class $g \in \mathcal{G}(0, d)$ if $f \sim g$ where $f(x)=s_{E}(\exp (-\exp (x)))$.
Of course, the covering class is only well-defined up to asymptotic equivalence. In general, if $E$ has covering class $g$, then $\underline{\operatorname{dim}}_{\mathrm{B}} E=\liminf _{x \rightarrow \infty} g(x)$ and $\operatorname{dim}_{\mathrm{B}} E=$ $\lim \sup _{x \rightarrow \infty} g(x)$. One can interpret the numbers $\lambda$ and $\alpha$ as saying that uniformly (in a weak exponential sense) over all pairs of scales and on average in space, $E$ is at least $\lambda$-dimensional and at most $\alpha$-dimensional.

By a straightforward argument given in Proposition 3.3, the class $\mathcal{G}(\lambda, \alpha)$ is closed under taking suprema and infima. Recalling Figure 1, we will use Theorem $C$ to prove the following result.
Theorem E. Let $\Lambda$ be the limit set of a CIFS on $\mathbb{R}^{d}$ with fixed points $F$. Let $F$ have covering class $f$ and let

$$
g \in \mathcal{G}\left(\operatorname{dim}_{\mathrm{H}} \Lambda, d\right)
$$

be the pointwise minimal function satisfying $f \leq g$. Then $\Lambda$ has covering class $g$.

Remark 1.7. If $F$ has covering class $f \in \mathcal{G}(0, \alpha)$, then we in fact prove that $\Lambda$ has covering class $g$ where $g \in \mathcal{G}\left(\operatorname{dim}_{\mathrm{H}} \Lambda, \max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \alpha\right\}\right)$ is the pointwise minimal function satisfying $f \leq g$. Moreover, in this case, the proof of Theorem D implies that the bound holds with $\alpha$ in place of $d$. In particular, by Proposition 3.5,

$$
\underline{\operatorname{dim}}_{\mathrm{B}} \Lambda \in \mathcal{D}\left(h, \underline{\operatorname{dim}}_{\mathrm{B}} F, \overline{\operatorname{dim}}_{\mathrm{B}} F, \operatorname{dim}_{\mathrm{qA}} F\right),
$$

where $\operatorname{dim}_{\mathrm{qA}} F$ is the quasi-Assouad dimension of $F$ introduced in [LX16].
1.5. Further research. There are several possible directions for future research. It is likely that methods in this paper would also extend to the case of the lower intermediate dimensions of the limit set of a CIFS, which would give a complete answer to [BF23, Question 3.7]. In another direction, little is known about the box dimensions of sets generated by countably many affine contractions, despite interest in the Hausdorff dimension of such sets [KM24+; KR14]. Some other work in this direction can be found in [GKK $+24+$ ].

We also note a connection with the study of inhomogeneous self-conformal sets. As established by Fraser [Fra12], the lower box dimension of the attractor of an inhomogeneous self-similar IFS also depends on the covering properties of the condensation set at different scales through the so-called covering regularity exponent. It seems plausible to the authors that the techniques in this paper would be useful in the study of box dimensions of inhomogeneous self-conformal sets.
1.6. Notation, conventions, and structure of paper. Throughout the paper, we work in $\mathbb{R}^{d}$ for $d \in \mathbb{N}$ equipped with the Euclidean norm. The ball $B(x, r)$ is the open ball centred at $x$ with radius $r$. The covering number $N_{r}(E)$ is the least number of open balls of radius $r$ required to cover $E$.

We will also find it useful to use asymptotic notation. Given a set $A$ and functions $f, g: A \rightarrow \mathbb{R}$, we write $f \lesssim g$ if there is a constant $C>0$ such that $f(a) \leq C g(a)$ for all $a \in A$. We write $f \approx g$ if $f \lesssim g$ and $f \gtrsim g$. The constants in the asymptotic notation will always be allowed to implicitly depend on the underlying IFS; any other dependence will be explicitly indicated by a subscript, such as $\lesssim_{\varepsilon}$.

In $\S 2$ we prove our key result Theorem C giving the asymptotic formula for covering numbers. In $\S 3$ we prove several consequences of Theorem C, including the bounds in the first half of Theorem D, as well as Theorem B (which determines when the box dimension exists), and Theorem E (describing the covering class of the limit set). Finally, in $\S 4$ we construct examples showing sharpness of certain bounds and completing the proof of Theorem D. We also construct examples of sets of continued fraction expansions with restricted digits (which are invariant for the Gauss map) and prove Theorem A.

## 2. AN ASYMPTOTIC FORMULA FOR COVERING NUMBERS

In this section, we prove our core result, which is Theorem C.
2.1. Bounded neighbourhood condition. In the introduction, we assumed that a CIFS satisfies the open set condition and the cone condition. In fact, throughout this section, the only separation assumption we will require is given in Definition 2.1 below.

We say that a subset $\mathcal{F} \subset \mathcal{I}^{*}$ is mutually incomparable if $i$ is not a prefix of $j$ for all $i, j \in \mathcal{F}$ with $i \neq j$.
Definition 2.1. We say that the IFS $\left\{S_{i}\right\}_{i \in \mathcal{I}}$ satisfies the bounded neighbourhood condition if there exists $M \in \mathbb{N}$ so that for all mutually incomparable $\mathcal{F} \subset \mathcal{I}^{*}$, for all $x \in X$, and for all $r \in(0,1)$,

$$
\#\left\{\mathrm{i} \in \mathcal{F}: \rho(\mathrm{i})>r \text { and } S_{\mathrm{i}}(X) \cap B(x, r) \neq \varnothing\right\} \leq M
$$

By a measure argument, it is straightforward to see that the open set condition and the cone condition together imply the bounded neighbourhood condition (see, for instance, [MU96, Lemma 2.7]).

In some sense, we require the open set condition and the cone condition (via [MU96]) to ensure that

$$
\operatorname{dim}_{\mathrm{H}} \Lambda=h:=\inf \{t \geq 0: P(t)<0\}
$$

Under the bounded neighbourhood condition, our proofs hold with the number $h$ in place of $\operatorname{dim}_{H} \Lambda$ and do not require any of the results from [MU96]. We emphasise that the bounded neighbourhood condition is morally very similar to the open set condition and the cone condition; it is likely the case that the results of [MU96] continue to hold only under the assumption of the bounded neighbourhood condition.
2.2. Regularity of covering numbers. In this section, we note two standard bounds on covering numbers.

The first bound is an immediate consequence of Ahlfors-David regularity of $\mathbb{R}^{d}$.

Lemma 2.2. Let $d \in \mathbb{N}$. Then there is a constant $A_{d} \geq 0$ so that for all non-empty bounded sets $E \subset \mathbb{R}^{d}$ and all $0<\theta \leq 1$,

$$
\theta s_{E}\left(r^{\theta}\right) \leq s_{E}(r) \leq d-\left(d-s_{E}\left(r^{\theta}\right)\right) \theta+\frac{A_{d}}{\log (1 / r)}
$$

Proof. On the one hand, $N_{r}(E)$ increases as $r$ decreases. On the other hand, since $\mathbb{R}^{d}$ is Ahlfors-David $d$-regular, there is a constant $C \geq 1$ (depending on $d$ ) so that for all $0<r \leq R$, each ball of radius $R$ can be covered by $C(R / r)^{d}$ balls of radius $r$. Thus for $0<r<1$, covering balls $B\left(x, r^{\theta}\right)$ by balls of radius $r$,

$$
N_{r^{\theta}}(E) \leq N_{r}(E) \leq C N_{r^{\theta}}(E)\left(\frac{r^{\theta}}{r}\right)^{d}
$$

Writing $A_{d}=\log (C)$, taking logarithms and rearranging yields the claim.

The second bound simply uses the definition of the upper box dimension.
Lemma 2.3. Let $d \in \mathbb{N}$ and $E \subset \mathbb{R}^{d}$ be non-empty and bounded. Then

$$
\lim _{r \rightarrow 0} \sup _{\theta \in(0,1]}\left(\theta s_{E}\left(r^{\theta}\right)-\theta \overline{\operatorname{dim}}_{\mathrm{B}} E\right)=0
$$

In particular, for all $0 \leq h \leq d$,

$$
\limsup _{r \rightarrow 0} \sup _{\theta \in(0,1]}\left((1-\theta) \cdot h+\theta s_{E}\left(r^{\theta}\right)\right)=\max \left\{h, \overline{\operatorname{dim}}_{\mathrm{B}} E\right\} .
$$

Proof. Let $\varepsilon>0$ be arbitrary and let $r_{0}$ be such that $s_{E}(r) \leq \overline{\operatorname{dim}}_{\mathrm{B}} E+\varepsilon$ for all $0<r \leq r_{0}$. Let $M=N_{r_{0}}(E)$ and let $0<r \leq r_{0}^{1 / \varepsilon}$ be sufficiently small so that

$$
\frac{\log M}{\log (1 / r)} \leq \varepsilon
$$

Then for all $0<\theta \leq 1$, if $\varepsilon \leq \theta \leq 1$, then

$$
\theta s_{E}\left(r^{\theta}\right) \leq \theta\left(\overline{\operatorname{dim}}_{\mathrm{B}} E+\varepsilon\right) \leq \theta \overline{\operatorname{dim}}_{\mathrm{B}} E+\varepsilon
$$

and if $0<\theta \leq \varepsilon$, then

$$
\theta s_{E}\left(r^{\theta}\right)=\frac{\log N_{r^{\theta}}(E)}{\log (1 / r)} \leq \frac{\log M}{\log (1 / r)} \leq \varepsilon \leq \theta \overline{\operatorname{dim}}_{\mathrm{B}} E+\varepsilon
$$

Thus for all $r$ sufficiently small,

$$
\sup _{\theta \in(0,1]}\left(\theta s_{E}\left(r^{\theta}\right)-\theta \overline{\operatorname{dim}}_{\mathrm{B}} E\right) \leq \varepsilon .
$$

Conversely, let $r_{0}>0$ be such that $s_{E}\left(r_{0}\right) \geq \overline{\operatorname{dim}}_{\mathrm{B}} E-\varepsilon$ and let $0<r \leq r_{0}$ be arbitrary. Let $\theta_{0}$ be such that $r^{\theta_{0}}=r_{0}$. Then

$$
\sup _{\theta \in(0,1)}\left(\theta s_{E}\left(r^{\theta}\right)-\theta \overline{\operatorname{dim}}_{\mathrm{B}} E\right) \geq \theta_{0}\left(\overline{\operatorname{dim}}_{\mathrm{B}} E-\varepsilon\right)-\theta_{0} \overline{\operatorname{dim}}_{\mathrm{B}} E \geq-\varepsilon .
$$

Since $\varepsilon>0$ was arbitrary, the first claim follows.
To prove the second claim, by considering $\theta=1$ and $\theta \rightarrow 0$ for each $r$, we see that

$$
\limsup _{r \rightarrow 0} \sup _{\theta \in(0,1]}\left((1-\theta) \cdot h+\theta s_{E}\left(r^{\theta}\right)\right) \geq \max \left\{h, \overline{\operatorname{dim}}_{\mathrm{B}} E\right\} .
$$

To obtain the upper bound, let $\varepsilon>0$ be arbitrary. Then for $r>0$ sufficiently small, by the first claim,

$$
\begin{aligned}
\sup _{\theta \in(0,1]}\left((1-\theta) \cdot h+\theta s_{E}\left(r^{\theta}\right)\right) & \leq \sup _{\theta \in(0,1]}\left((1-\theta) \cdot h+\theta \overline{\operatorname{dim}}_{\mathrm{B}} E\right)+\varepsilon \\
& \leq \max \left\{h, \overline{\operatorname{dim}}_{\mathrm{B}} E\right\}+\varepsilon .
\end{aligned}
$$

Since $\varepsilon>0$ was arbitrary, the second claim follows.
2.3. Properties of the lower box dimension formula. In the statement of Theorem C, an asymptotic formula for $N_{r}(\Lambda)$ is established in terms of the function $\psi(r)$. In particular, $\psi(r)$ depends implicitly on the precise choice $F$. By taking a higher power, the associated set of fixed points is larger so the associated estimate could in principle be different. Moreover, one might also consider alternatives to the set of fixed points, such as the orbit sets

$$
\mathcal{O}(x, m):=\left\{S_{\mathrm{i}}(x): \mathrm{i} \in \mathcal{I}^{m}\right\}
$$

defined for $x \in X$ and $n \in \mathbb{N}$. For example, this is the choice made in [MU99]. Of course, since none of these operations change $N_{r}(\Lambda)$, if Theorem C is to be true, then they also certainly cannot change the asymptotics of the corresponding definition of $\psi(r)$.

In this section, we establish some basic properties of the function $\psi$. In particular, we will see that there is flexibility in the choice of the set $F$, and moreover show that $\psi(r)$ does not depend on the initial level of iteration (up to some error term which is asymptotically 0 ). These results will also be required in our proof of Theorem C.

We now make our definitions precise. Let $E \subset X$ be an arbitrary bounded non-empty set. We define

$$
\begin{aligned}
\Psi_{E}(r, \theta) & =(1-\theta) \operatorname{dim}_{H} \Lambda+\frac{\log N_{r^{\theta}}(E)}{\log (1 / r)} \\
\psi_{E}(r) & =\liminf _{r \rightarrow 0} \max _{\theta \in[0,1]} \Psi_{E}(r, \theta) .
\end{aligned}
$$

The maximum in the definition of $\psi_{E}(r)$ is attained because the covering number $N_{r}$ is defined in terms of open balls, so the map $\theta \mapsto N_{r^{\theta}}(E)$ is upper semicontinuous.

Definition 2.4. Let $\left\{S_{i}\right\}_{i \in \mathcal{I}}$ be a CIFS on a compact set $X$. We say a set $E \subset$ $\bigcup_{i \in \mathcal{I}} S_{i}(X)$ is a discrete approximation of $\left\{S_{i}\right\}_{i \in \mathcal{I}}$ if there is a number $k \in \mathbb{N}$ so that $1 \leq \#\left(E \cap S_{i}(x)\right) \leq k$ for all $i \in \mathcal{I}$.

For instance, the set of fixed points $F$ and the orbit sets $\mathcal{O}(x, 1)$ for $x \in X$ are discrete approximations.

Lemma 2.5. Let $\left\{S_{i}\right\}_{i \in \mathcal{I}}$ be a CIFS on a compact set $X$. Suppose $E_{1}$ and $E_{2}$ are discrete approximations of $\left\{S_{i}\right\}_{i \in \mathcal{I}}$. Then $N_{r}\left(E_{1}\right) \approx N_{r}\left(E_{2}\right)$, uniformly for $r \in(0,1)$. In particular,

$$
\lim _{r \rightarrow 0}\left(\psi_{E_{1}}(r)-\psi_{E_{2}}(r)\right)=0 .
$$

Proof. This holds by the same argument as the proof of [MU99, Proposition 2.9], which depends on the bounded neighbourhood condition.

Next, we consider higher iterates of the CIFS. With Lemma 2.5 in mind, for convenience we may restrict our attention to the orbit sets $\mathcal{O}\left(x_{0}, m\right)$, where $m \in \mathbb{N}$,
and $x_{0} \in X$ is chosen so that $S_{i}\left(x_{0}\right)=x_{0}$ for some $i \in \mathcal{I}$. Write $F_{m}:=\mathcal{O}\left(x_{0}, m\right)$. With $x_{0}$ chosen in this way,

$$
\begin{equation*}
F_{m}=\bigcup_{\mathbf{i} \in \mathcal{I}^{m-1}} S_{\mathrm{i}}\left(F_{1}\right) \subset \Lambda . \tag{2.1}
\end{equation*}
$$

For each $m \in \mathbb{N}$, as shorthand, we also write $\Psi_{m}:=\Psi_{F_{m}}, \psi_{m}:=\psi_{F_{m}}$, and for $0<r<1$

$$
s_{m}(r):=\frac{\log N_{r}\left(F_{m}\right)}{\log (1 / r)} .
$$

Next, for each $i \in \mathcal{I}^{*}$ with $\rho(i)>r$, let $\theta_{i}(r) \in(0,1]$ be given by

$$
\theta_{\mathbf{i}}(r):=1-\frac{\log \rho(\mathrm{i})}{\log r} .
$$

Equivalently, $\theta_{\mathbf{i}}(r)$ is chosen so that

$$
\begin{equation*}
N_{r . \rho(\mathrm{i})^{-1}}\left(F_{1}\right)=\rho(\mathrm{i})^{\operatorname{dim}_{\mathrm{H}} \Lambda} \cdot\left(\frac{1}{r}\right)^{\Psi_{1}\left(r, \theta_{\mathrm{i}}(r)\right)} . \tag{2.2}
\end{equation*}
$$

For $m \in \mathbb{N}$ and $0<r<1$, we also write

$$
E_{m}(r):=\bigcup_{\substack{\mathrm{i} \in \mathcal{I}^{m} \\ \rho(\mathrm{i}) \leq r}} S_{\mathrm{i}}(\Lambda)
$$

Since $E_{m}(r)$ is contained in the $(r \cdot \operatorname{diam} X)$-neighbourhood of $F$,

$$
\begin{equation*}
N_{r}\left(E_{m}(r)\right) \lesssim N_{r}(F) \tag{2.3}
\end{equation*}
$$

We now establish invariance under higher iterates.
Lemma 2.6. Let $\left\{S_{i}\right\}_{i \in \mathcal{I}}$ be a CIFS. Then for each $m \in \mathbb{N}$,

$$
\lim _{r \rightarrow 0}\left(\psi_{1}(r)-\psi_{m}(r)\right)=0
$$

Proof. It is clear that $\psi_{1} \leq \psi_{2} \leq \cdots \leq \psi_{m}$ for $m \in \mathbb{N}$. Thus it suffices to prove that for all $\varepsilon>0$ and all $m \in \mathbb{N}$ sufficiently large,

$$
\begin{equation*}
\limsup _{r \rightarrow 0}\left(\psi_{m}(r)-\psi_{1}(r)\right) \leq 2 \varepsilon \tag{2.4}
\end{equation*}
$$

Fix $\varepsilon>0$. By the definition of the pressure, let $m \in \mathbb{N}$ be sufficiently large so that

$$
\begin{equation*}
\sum_{\mathbf{i} \in \mathcal{I}^{m-1}} \rho(\mathbf{i})^{\operatorname{dim}_{H} \Lambda+\varepsilon}<\infty . \tag{2.5}
\end{equation*}
$$

We first show that

$$
\begin{equation*}
\limsup _{r \rightarrow 0}\left(s_{m}(r)-\psi_{1}(r)\right) \leq \varepsilon \tag{2.6}
\end{equation*}
$$

Let $\varepsilon>0$ be arbitrary. For each $r \in(0,1)$, recalling (2.1) and (2.3),

$$
\begin{aligned}
N_{r}\left(F_{n}\right) & =N_{r}\left(\bigcup_{\mathbf{i} \in \mathcal{I}^{m-1}} S_{\mathbf{i}}\left(F_{1}\right)\right) \\
& \lesssim N_{r}\left(F_{1}\right)+\sum_{\substack{\mathbf{i} \in \mathcal{I}^{m-1} \\
\rho(\mathbf{i})>r}} N_{r \cdot \rho(\mathrm{i})^{-1}}\left(F_{1}\right) \\
& =N_{r}\left(F_{1}\right)+\sum_{\substack{\mathrm{i} \in \mathcal{I}^{m-1} \\
\rho(\mathbf{i})>r}} \rho(\mathrm{i})^{\operatorname{dim}_{\mathrm{H}} \Lambda} \cdot\left(\frac{1}{r}\right)^{\Psi_{1}\left(r, \theta_{\mathrm{i}}(r)\right)} \\
& \leq N_{r}\left(F_{1}\right)+\left(\frac{1}{r}\right)^{\psi_{1}(r)+\varepsilon} \sum_{\mathbf{i} \in \mathcal{I}^{m-1}} \rho(\mathrm{i})^{\operatorname{dim}_{\mathrm{H}} \Lambda+\varepsilon} \\
& \lesssim\left(\frac{1}{r}\right)^{\psi_{1}(r)+\varepsilon} .
\end{aligned}
$$

In the last line, we used (2.5) and the observation that $s_{1}(r)=\Psi_{1}(r, 1) \leq \psi_{1}(r)$. The above calculation is equivalent to the fact that there is a constant $C>0$ so that

$$
s_{m}(r) \leq \psi_{1}(r)+\frac{C}{\log (1 / r)}+\varepsilon .
$$

Thus (2.6) follows.
We now establish (2.4). Let $r \in(0,1)$ be small, let $\theta$ be chosen so that $\psi_{m}(r)=$ $\Psi_{m}(r, \theta)$, and let $\kappa$ be chosen so that $\psi_{1}(r)=\Psi_{1}(r, \kappa)$. By the definition of $\kappa$ and using (2.6), for all $r$ sufficiently small,

$$
\begin{aligned}
\psi_{m}(r) & =(1-\theta) \operatorname{dim}_{\mathrm{H}} \Lambda+\theta s_{m}\left(r^{\theta}\right) \\
& \leq(1-\theta) \operatorname{dim}_{\mathrm{H}} \Lambda+\theta\left((1-\kappa) \operatorname{dim}_{\mathrm{H}} \Lambda+\kappa s_{1}\left(r^{\theta \kappa}\right)+2 \varepsilon\right) \\
& =\Psi_{1}(r, \theta \kappa)+2 \theta \varepsilon \\
& \leq \psi_{1}(r)+2 \varepsilon
\end{aligned}
$$

Thus (2.4) follows, and therefore the desired result holds.
2.4. Proof of the asymptotic formula. In this section, we establish our main asymptotic formula for $N_{r}(\Lambda)$, as stated in Theorem C.

First, for each $m \in \mathbb{N}$, define

$$
\tau_{m}(r):=\sum_{\substack{\mathbf{i} \in\left(\mathcal{I}^{m}\right)^{*} \\ \rho(\mathrm{i})>r}} N_{r \cdot \rho(\mathrm{i})^{-1}}\left(F_{m}\right)=\sum_{\substack{\mathrm{i} \in\left(\mathcal{I}^{m}\right)^{*} \\ \rho(\mathrm{i})>r}} \rho(\mathrm{i})^{\operatorname{dim}_{\mathrm{H}} \Lambda}\left(\frac{1}{r}\right)^{\Psi_{m}\left(r, \theta_{\mathrm{i}}(r)\right)}
$$

We first reduce the question of bounding the covering numbers $N_{r}(\Lambda)$ to the question of bounding the symbolic counts $\tau_{m}(r)$.
Lemma 2.7. Let $\left\{S_{i}\right\}_{i \in \mathcal{I}}$ be a CIFS with attractor $\Lambda$ and fixed points $F$. Then for all $\varepsilon>0$ and $m \in \mathbb{N}$ sufficiently large, there exists $C \geq 1$ so that for all $0<r<1$,

$$
C^{-1} r^{\varepsilon} \tau_{m}(r) \leq N_{r}(\Lambda) \leq C r^{-\varepsilon} \tau_{m}(r) .
$$

Proof. The result will follow from the following key estimate: there exists a constant $C_{0} \geq 1$ so that for all $m \in \mathbb{N}$ and $0<r<1$,

$$
\begin{equation*}
C_{0}^{-1} \cdot N_{r}(\Lambda) \leq N_{r}\left(F_{m}\right)+\sum_{\substack{\mathrm{i} \in \mathcal{I}^{m} \\ \rho(\mathrm{i})>r}} N_{r \cdot \rho\left(\mathrm{i}^{-1}\right)}(\Lambda) \leq C_{0} \cdot N_{r}(\Lambda) \tag{2.7}
\end{equation*}
$$

Critically, the constant $C_{0}$ is independent of $m$ and $r$. Suppose this estimate holds. Recalling that $\xi=\sup _{i \in \mathcal{I}} \rho(i) \in(0,1)$, take $k \in \mathbb{N}$ be minimal so that $\xi^{k m} \leq r$. Then applying (2.7) $k$ times gives,

$$
N_{r}(\Lambda) \leq \sum_{\substack{\mathbf{i} \in\left(\mathcal{I}^{m}\right)^{*} \\ \rho(\mathrm{i})>r \text { and }|\mathrm{i}|<k}} C_{0}^{|\mathrm{i}|+1} \cdot N_{r \cdot \rho(\mathrm{i})^{-1}}\left(F_{m}\right) \leq C_{0}^{k} \tau_{m}(r)
$$

The lower bound $C_{0}^{-k} \tau_{m}(r) \leq N_{r}(\Lambda)$ also holds by the same argument. Then, given $\varepsilon>0$, let $m$ be sufficiently large so that $\frac{\log C_{0}}{m \log (1 / \xi)} \leq \varepsilon$ and, since $\xi^{(k-1) m}>r$,

$$
C_{0}^{-1} r^{\varepsilon} \tau_{m}(r) \leq C_{0}^{-k} \tau_{m}(r) \leq N_{r}(\Lambda) \leq C_{0}^{k} \tau_{m}(r) \leq C_{0} r^{-\varepsilon} \tau_{m}(r)
$$

which is the desired result.
It remains to establish (2.7). By the invariance property of $\Lambda$,

$$
\Lambda=E_{m}(r) \cup \bigcup_{\substack{i \in \mathcal{I}^{m} \\ \rho(\mathrm{i})>r}} S_{\mathrm{i}}(\Lambda)
$$

Thus by (2.3), since $N_{r}\left(S_{\mathrm{i}}(\Lambda)\right) \approx N_{r \cdot \rho(\mathrm{i})^{-1}}(\Lambda)$,

$$
N_{r}(\Lambda) \lesssim N_{r}\left(F_{m}\right)+\sum_{\substack{i \in \mathcal{T}^{m} \\ \rho(\mathbf{i})>r}} N_{r \cdot \rho(\mathbf{i})^{-1}}(\Lambda)
$$

We now obtain the other bound. First, by the bounded neighbourhood condition,

$$
\sum_{\substack{\mathbf{i} \in \mathcal{I}^{m} \\ \rho(\mathrm{i})>r}} N_{r}\left(S_{\mathrm{i}}(\Lambda)\right) \leq M \cdot N_{r}\left(\bigcup_{\substack{i \in \mathcal{I}^{m} \\ \rho(\mathrm{i})>r}} S_{\mathrm{i}}(\Lambda)\right) \leq M \cdot N_{r}(\Lambda)
$$

Therefore since $N_{r}\left(F_{m}\right) \leq N_{r}(\Lambda)$,

$$
N_{r}\left(F_{m}\right)+\sum_{\substack{\mathbf{i} \in \mathcal{I}^{m} \\ \rho(\mathbf{i})>r}} N_{r \cdot \rho(\mathbf{i})^{-1}}(\Lambda) \lesssim(M+1) \cdot N_{r}(\Lambda) .
$$

Thus (2.7) follows.
Next, we require the standard observation for finite iterated function systems that the Hausdorff dimension is realised uniformly over all scales.

Lemma 2.8. Let $\left\{S_{i}\right\}_{i \in \mathcal{I}}$ be a CIFS with limit set $\Lambda$, and suppose $\mathcal{I}$ is a finite index set. Let $\rho_{\text {min }}=\min \{\rho(i): i \in \mathcal{I}\}>0$. Then for all $s<\operatorname{dim}_{H} \Lambda$, with

$$
\mathcal{I}(r):=\left\{\mathrm{i} \in \mathcal{I}^{*}: r<\rho(\mathrm{i}) \leq r K \rho_{\min }^{-1}\right\},
$$

we have $\# \mathcal{I}(r) \gtrsim r^{-s}$.
Proof. Since $\mathcal{I}$ is finite, $\operatorname{dim}_{\mathrm{B}} \Lambda=\operatorname{dim}_{\mathrm{H}} \Lambda$. Moreover, by (1.1), every infinite word $\gamma \in \mathcal{I}^{\mathbb{N}}$ has at least one prefix in $\mathcal{I}(r)$, so $\left\{S_{\mathrm{i}}(X): \mathrm{i} \in \mathcal{I}(r)\right\}$ is a cover for $\Lambda$.

Now fix $s<\operatorname{dim}_{\mathrm{B}} \Lambda$ and let $r>0$ be small. Get a pairwise-disjoint family of balls $\left\{B\left(x_{i}, r\right)\right\}_{i=1}^{N}$ with $N \gtrsim r^{-s}$ and each $x_{i} \in X$. Thus by the bounded neighbourhood condition, $\# \mathcal{I}(r) \geq M^{-1} N \gtrsim r^{-s}$, as claimed.

We also need a simple continuity property of the function $\Psi(r, \theta)$ in $\theta$.
Lemma 2.9. There is a constant $A_{d} \geq 0$ so that for all $m \in \mathbb{N}, \theta_{1}, \theta_{2} \in[0,1]$ and $0<r<1$,

$$
\left|\Psi_{m}\left(r, \theta_{1}\right)-\Psi_{m}\left(r, \theta_{2}\right)\right| \leq 2 d\left|\theta_{1}-\theta_{2}\right|+\frac{A_{d}}{\log (1 / r)}
$$

Proof. Let $m \in \mathbb{N}$ and $0<r<1$. Without loss of generality, we may fix $0 \leq \theta_{1} \leq \theta_{2} \leq 1$. Then by Lemma 2.2,

$$
\begin{aligned}
\left|\Psi_{m}\left(r, \theta_{1}\right)-\Psi_{m}\left(r, \theta_{2}\right)\right| & \leq\left(\theta_{2}-\theta_{1}\right) \operatorname{dim}_{\mathrm{H}} \Lambda+\left|\frac{\log N_{r^{\theta_{2}}}\left(F_{m}\right)}{\log (1 / r)}-\frac{\log N_{r^{\theta_{1}}}\left(F_{m}\right)}{\log (1 / r)}\right| \\
& \leq\left(\theta_{2}-\theta_{1}\right) d+\frac{A_{d}}{\log (1 / r)}+\left(\theta_{2}-\theta_{1}\right) d
\end{aligned}
$$

as claimed.
We now have all of the tools required to prove our main formula, which we restate below for the convenience of the reader.

Restatement (of Theorem C). Let $\Lambda$ be the limit set of a CIFS on $\mathbb{R}^{d}$ with fixed points $F$ and associated function $\psi$. Then

$$
\lim _{r \rightarrow 0}\left(\frac{\log N_{r}(\Lambda)}{\log (1 / r)}-\psi(r)\right)=0
$$

In particular,

$$
\underline{\operatorname{dim}}_{\mathrm{B}} \Lambda=\liminf _{r \rightarrow 0} \psi(r) .
$$

Proof. By Lemmas 2.5 and 2.6, it suffices to show that for all $\varepsilon>0$, there exists $m \in \mathbb{N}$ so that for all $r>0$ sufficiently small,

$$
-6 \varepsilon \leq \frac{\log N_{r}(\Lambda)}{\log (1 / r)}-\psi_{m}(r) \leq 2 \varepsilon
$$

We begin with the upper bound. First, let $m \in \mathbb{N}$ be sufficiently large so that

$$
\begin{equation*}
\sum_{i \in \mathcal{I}^{m}} \rho(\mathrm{i})^{\operatorname{dim}_{H} \Lambda+\varepsilon}=: \vartheta<1, \tag{2.8}
\end{equation*}
$$

and moreover for all $r>0$ sufficiently small

$$
\frac{\log N_{r}(\Lambda)}{\log (1 / r)} \leq \frac{\log \tau_{m}(r)}{\log (1 / r)}+\varepsilon
$$

The second choice is possible by Lemma 2.7. The choice (2.8) implies by submultiplicativity of $\rho$ that

$$
\begin{aligned}
\sum_{\mathbf{i} \in\left(\mathcal{I}^{m}\right)^{*}} \rho(\mathrm{i})^{\operatorname{dim}_{\mathrm{H}} \Lambda+\varepsilon} & =\sum_{k=0}^{\infty} \sum_{\mathrm{i}_{1} \in \mathcal{I}^{m}} \cdots \sum_{\mathbf{i}_{k} \in \mathcal{I}^{m}} \rho\left(\mathrm{i}_{1} \cdots \mathrm{i}_{k}\right)^{\operatorname{dim}_{\mathbf{H}} \Lambda+\varepsilon} \\
& \leq \sum_{k=0}^{\infty}\left(\sum_{\mathrm{i} \in \mathcal{I}^{m}} \rho(\mathbf{i})^{\operatorname{dim}_{\mathbf{H}} \Lambda+\varepsilon}\right)^{k} \\
& =\sum_{k=0}^{\infty} \vartheta^{k}<\infty .
\end{aligned}
$$

Therefore

$$
\begin{aligned}
\tau_{m}(r) & =\sum_{\substack{\mathbf{i} \in\left(\mathcal{I}^{m}\right)^{*} \\
\rho(\mathbf{i})>r}} \rho(\mathrm{i})^{\operatorname{dim}_{\mathrm{H}} \Lambda} \cdot\left(\frac{1}{r}\right)^{\Psi_{m}\left(r, \theta_{\mathrm{i}}(r)\right)} \\
& \leq\left(\frac{1}{r}\right)^{\psi_{m}(r)+\varepsilon} \sum_{\substack{\mathrm{i} \in\left(\mathcal{I}^{m}\right)^{*} \\
\rho(\mathbf{i})>r}} \rho(\mathrm{i})^{\operatorname{dim}_{\mathrm{H}} \Lambda+\varepsilon} \\
& \lesssim \varepsilon\left(\frac{1}{r}\right)^{\psi_{m}(r)+\varepsilon} .
\end{aligned}
$$

We now establish the lower bound. Heuristically, the upper bound proven above is sharp if the sum of the $\rho(i)^{\operatorname{dim}_{H} \Lambda}$ is realised uniformly over all scales simultaneously so that the error which results from bounding $\Psi_{m}(r, \cdot)$ by the supremum $\psi_{m}(r)$ is small. This follows by approximation via finite subsystems as a direct consequence of Lemma 2.8.

Let $m \in \mathbb{N}$ be sufficiently large so that there is a finite subset $\mathcal{F} \subset \mathcal{I}^{m}$ such that the CIFS $\left\{S_{\mathrm{i}}\right\}_{\mathrm{i} \in \mathcal{F}}$ has limit set $\Lambda_{\varepsilon}$ with

$$
s:=\operatorname{dim}_{H} \Lambda_{\varepsilon}>\operatorname{dim}_{H} \Lambda-\varepsilon,
$$

and moreover for all $r>0$ sufficiently small

$$
\frac{\log N_{r}(\Lambda)}{\log (1 / r)} \geq \frac{\log \tau_{m}(r)}{\log (1 / r)}-\varepsilon .
$$

That the first choice is possible follows from [MU96, Theorem 3.15], and again the second choice is possible by Lemma 2.7. Next, fix the constant $A_{d}$ from Lemma 2.9, let $r$ be sufficiently small so that $A_{d} / \log (1 / r) \leq \varepsilon$, and fix a partition $0=\kappa_{0}<\kappa_{1}<\cdots<\kappa_{\ell}=1$ such that $\kappa_{i}-\kappa_{i-1} \leq(2 d)^{-1} \varepsilon$ for all $i=1, \ldots, \ell$. Now for each $i=1, \ldots, \ell$ and $r \in(0,1)$, set

$$
\begin{aligned}
\mathcal{F}_{i}^{*}(r) & =\left\{\mathrm{i} \in \mathcal{F}^{*}: \rho(\mathrm{i})>r ; \kappa_{i-1} \leq 1-\theta_{\mathrm{i}}(r)<\kappa_{i}\right\} \\
& =\left\{\mathrm{i} \in \mathcal{F}^{*}: r^{\kappa_{i}}<\rho(\mathrm{i}) \leq r^{\kappa_{i-1}}\right\} .
\end{aligned}
$$

Note that if $\mathrm{i} \in \mathcal{F}_{i}^{*}(r)$, by Lemma 2.9 and the choice of the $\kappa_{i}$, for all $r$ sufficiently small,

$$
\begin{equation*}
\Psi_{m}\left(r, \theta_{\mathrm{i}}(r)\right) \geq \Psi_{m}\left(r, 1-\kappa_{i}\right)-2 \varepsilon \tag{2.9}
\end{equation*}
$$

Now, let $r$ moreover be sufficiently small so that for all $i=1, \ldots, \ell$,

$$
K \rho_{\mathcal{F}}^{-1} r^{\kappa_{i}} \leq r^{\kappa_{i-1}} \quad \text { where } \quad \rho_{\mathcal{F}}:=\min \{\rho(\mathrm{i}): \mathrm{i} \in \mathcal{F}\}
$$

Thus for such $r$ and all $i=1, \ldots, \ell$, by Lemma 2.8,

$$
\# \mathcal{F}_{i}^{*}(r) \geq \#\left\{\mathbf{i} \in \mathcal{F}^{*}: r^{\kappa_{i}}<\rho(\mathbf{i}) \leq K \rho_{\mathcal{F}}^{-1} r^{\kappa_{i}}\right\} \gtrsim \varepsilon r^{-\kappa_{i}\left(\operatorname{dim}_{H} \Lambda-\varepsilon\right)},
$$

hence

$$
\sum_{\mathrm{i} \in \mathcal{F}_{i}^{*}(r)} \rho(\mathrm{i})^{\operatorname{dim}_{\mathrm{H}} \Lambda-\varepsilon} \geq \# \mathcal{F}_{i}^{*}(r) r^{\kappa_{i}\left(\operatorname{dim}_{\mathrm{H}} \Lambda-\varepsilon\right)} \gtrsim \varepsilon 1
$$

Thus for all $r$ sufficiently small,

$$
\begin{aligned}
\tau_{m}(r) & =\sum_{\substack{\mathrm{i} \in\left(\mathcal{I}^{m}\right)^{*} \\
\rho(\mathrm{i})>r}} \rho(\mathrm{i})^{\operatorname{dim}_{\mathrm{H}} \Lambda} \cdot\left(\frac{1}{r}\right)^{\Psi_{m}\left(r, \theta_{\mathrm{i}}(r)\right)} \\
& \geq \sum_{i=1}^{\ell}\left(\frac{1}{r}\right)^{\Psi_{m}\left(r, 1-\kappa_{i}\right)-3 \varepsilon} \sum_{\mathrm{i} \in \mathcal{F}_{i}^{*}(r)} \rho(\mathrm{i})^{\operatorname{dim}_{\mathrm{H}} \Lambda-\varepsilon} \\
& \gtrsim \varepsilon \max _{i=1, \ldots, \ell}\left(\frac{1}{r}\right)^{\Psi_{m}\left(r, 1-\kappa_{i}\right)-3 \varepsilon} \\
& \geq\left(\frac{1}{r}\right)^{\psi_{m}(r)-5 \varepsilon}
\end{aligned}
$$

In the last line, we again applied Lemma 2.9 using the observation that $\left\{\kappa_{1}, \ldots, \kappa_{l}\right\}$ is $(2 d)^{-1} \varepsilon$-dense in $[0,1]$. Since $\varepsilon>0$ was arbitrary, the desired result follows.

In [MU96, Theorem 3.1] it was shown that the packing dimension, which is the same as the modified upper box dimension, always coincides with upper box dimension for the attractor of a CIFS. Of course, the analogous result holds for modified lower box dimension, which is defined by

$$
\underline{\operatorname{dim}}_{\mathrm{MB}} K=\inf \left\{\sup _{i} \underline{\operatorname{dim}}_{\mathrm{B}} K_{i}: K \subset \bigcup_{i=1}^{\infty} K_{i}\right\} .
$$

This is a standard consequence of the Baire category theorem (see, e.g., [Fal14, Proposition 2.8]).

Proposition 2.10. Let $\Lambda$ be the limit set of a CIFS. Then $\underline{\operatorname{dim}}_{\mathrm{MB}} \Lambda=\operatorname{dim}_{\mathrm{B}} \Lambda$.

## 3. CONSEQUENCES OF THE ASYMPTOTIC FORMULA

In this section, we obtain consequences of the asymptotic formula stated in Theorem C .
3.1. Classifying existence of the box dimension. Using our formula for the lower box dimension stated in Theorem C, we obtain bounds on the lower box dimension in terms of $\operatorname{dim}_{\mathrm{H}} \Lambda, \underline{\operatorname{dim}}_{\mathrm{B}} F,{\operatorname{dim}_{\mathrm{B}}} F$, and the ambient dimension $d$, without any other information concerning the set $F$. Recalling the general bounds from (1.4), this implies the first half of Theorem D.

Corollary 3.1. Let $\Lambda$ be the limit set of a CIFS on $\mathbb{R}^{d}$. Then if $\overline{\operatorname{dim}}_{\mathrm{B}} F>\operatorname{dim}_{\mathrm{H}} \Lambda$,

$$
\underline{\operatorname{dim}}_{\mathrm{B}} \Lambda \leq h+\frac{\left(\overline{\operatorname{dim}}_{\mathrm{B}} F-\operatorname{dim}_{\mathrm{H}} \Lambda\right)\left(d-\operatorname{dim}_{\mathrm{H}} \Lambda\right){\underset{\operatorname{dim}}{\mathrm{B}}} F}{d \overline{\operatorname{dim}}_{\mathrm{B}} F-\operatorname{dim}_{\mathrm{H}} F \cdot \underline{\operatorname{dim}}_{\mathrm{B}} F} .
$$

Proof. For notational simplicity, write $s=\operatorname{dim}_{\mathrm{B}} F, t=\overline{\operatorname{dim}}_{\mathrm{B}} F$, and $h=\operatorname{dim}_{\mathrm{H}} \Lambda$. Note that $h<t \leq d$, so we may set

$$
\theta_{d}=\frac{(d-h) t}{d \cdot t-h \cdot s} \leq 1
$$

Let $\left(r_{n}\right)_{n=1}^{\infty}$ be a sequence converging to zero such that

$$
\underline{\operatorname{dim}}_{\mathrm{B}} F=\liminf _{r \rightarrow 0} s_{F}(r)=\lim _{n \rightarrow \infty} s_{F}\left(r_{n}^{\theta_{d}}\right)
$$

Let $\varepsilon>0$ and let $n$ be sufficiently large so that $s_{F}\left(r_{n}^{\theta_{d}}\right) \leq s+\varepsilon$ and $\theta s_{F}\left(r_{n}^{\theta}\right) \leq$ $\theta \overline{\operatorname{dim}}_{\mathrm{B}} F+\varepsilon$ for all $0<\theta \leq 1$ by Lemma 2.3. By Theorem C and the definition of $\theta_{d}$, it suffices to show that for all $0<\theta \leq 1$,

$$
(1-\theta) \cdot h+\theta s_{F}\left(r_{n}^{\theta}\right) \leq d-(d-s) \theta_{d}+\varepsilon
$$

We consider three cases depending on the value of $\theta$.

1. $\theta_{d} \leq \theta \leq 1$. Then by Lemma 2.2,

$$
\begin{aligned}
s_{F}\left(r_{n}^{\theta}\right) & \leq d-\left(d-s_{F}\left(r_{n}^{\theta_{d}}\right)\right) \frac{\theta_{d}}{\theta} \\
& \leq d-(d-s) \theta_{d}+\varepsilon .
\end{aligned}
$$

Thus since $t>h$,

$$
\begin{aligned}
(1-\theta) h+\theta s_{F}\left(r_{n}^{\theta}\right) & \leq \max \left\{h, d-(d-s) \theta_{d}\right\}+\theta_{d} \varepsilon \\
& =d-(d-s) \theta_{d}+\varepsilon .
\end{aligned}
$$

2. $\theta_{d} \cdot s / t<\theta \leq \theta_{d}$. Then by Lemma 2.2,

$$
\begin{aligned}
(1-\theta) h+\theta s_{F}\left(r_{n}^{\theta}\right) & \leq(1-\theta) h+\theta_{d} s_{F}\left(r_{n}^{\theta_{d}}\right) \\
& \leq(1-\theta) h+\theta_{d} s+\theta_{d} \varepsilon \\
& \leq d-(d-s) \theta_{d}+\varepsilon .
\end{aligned}
$$

Here, the final inequality is equivalent to the lower bound on $\theta$.
3. $0<\theta \leq \theta_{d} \cdot s / t$. Then since $t>h$,

$$
\begin{aligned}
(1-\theta) h+\theta s_{F}\left(r_{n}^{\theta}\right) & \leq h+\theta(t-h)+\varepsilon \\
& \leq h+\theta_{d}\left(s-\frac{h s}{t}\right)+\varepsilon \\
& =d-(d-s) \theta_{d}+\varepsilon .
\end{aligned}
$$

This covers all the possible values of $\theta$, as required.
From this bound, it is straightforward to deduce our main classification result on the existence of the box dimension.

Restatement (of Theorem B). Let $\Lambda$ be the limit set of a CIFS. Then $\operatorname{dim}_{B} \Lambda=\overline{\operatorname{dim}}_{\mathrm{B}} \Lambda$ if and only if

$$
\overline{\operatorname{dim}}_{\mathrm{B}} F \leq \max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \underline{\operatorname{dim}}_{\mathrm{B}} F\right\} .
$$

Proof. First, suppose

$$
\overline{\operatorname{dim}}_{\mathrm{B}} F \leq \max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \operatorname{dim}_{\mathrm{B}} F\right\} .
$$

Then

$$
\begin{aligned}
\max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \underline{\operatorname{dim}}_{\mathrm{B}} F\right\} & \leq \operatorname{\operatorname {dim}}_{\mathrm{B}} \Lambda \\
& \leq \overline{\operatorname{dim}}_{\mathrm{B}} \Lambda \\
& =\max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \overline{\operatorname{dim}}_{\mathrm{B}} F\right\} \\
& \leq \max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \underline{\operatorname{dim}}_{\mathrm{B}} F\right\}
\end{aligned}
$$

so in fact equality holds, as claimed.
Conversely, suppose

$$
\overline{\operatorname{dim}}_{\mathrm{B}} F>\max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \underline{\operatorname{dim}}_{\mathrm{B}} F\right\} .
$$

Since $\overline{\operatorname{dim}}_{\mathrm{B}} \Lambda=\max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda, \overline{\operatorname{dim}}_{\mathrm{B}} F\right\}$, this implies that

$$
\overline{\operatorname{dim}}_{\mathrm{B}} \Lambda=\overline{\operatorname{dim}}_{\mathrm{B}} F \quad \text { and } \quad 1-\frac{\operatorname{dim}_{\mathrm{B}} F}{\overline{\operatorname{dim}}_{\mathrm{B}} F}>0
$$

Thus by Theorem D (or, more precisely, the limiting bound as explained in Remark 1.3),

$$
\underline{\operatorname{dim}}_{\mathrm{B}} \Lambda \leq \underline{\operatorname{dim}}_{\mathrm{B}} F+\left(1-\frac{\operatorname{dim}_{\mathrm{B}} F}{\overline{\operatorname{dim}}_{\mathrm{B}} F}\right) \operatorname{dim}_{\mathrm{H}} \Lambda
$$

$$
\begin{aligned}
& <\underline{\operatorname{dim}}_{\mathrm{B}} F+\left(1-\frac{\operatorname{dim}_{\mathrm{B}} F}{\overline{\operatorname{dim}}_{\mathrm{B}} F}\right) \overline{\operatorname{dim}}_{\mathrm{B}} F \\
& =\overline{\operatorname{dim}}_{\mathrm{B}} F \\
& =\overline{\operatorname{dim}}_{\mathrm{B}} \Lambda
\end{aligned}
$$

as claimed.
3.2. Some preliminaries on the covering class. In this section, we provide an introduction to the covering class and in particular prove Proposition 1.5. We recall the various definitions from $\S 1.4$. We also note an equivalent integrated version of the definition of $\mathcal{G}(\lambda, \alpha)$. This is a consequence of the mean value theorem for one-sided derivatives of continuous functions; for a proof, see for instance [BR22, Lemma 3.2].

Lemma 3.2. Let $0 \leq \lambda \leq \alpha \leq d$ and let $g: \mathbb{R} \rightarrow \mathbb{R}$. Then $g \in \mathcal{G}(\lambda, \alpha)$ if and only if for all $x_{0} \in \mathbb{R}$ and $x>0$,

$$
\lambda-\left(\lambda-g\left(x_{0}\right)\right) \exp (-x) \leq g\left(x_{0}+x\right) \leq \alpha-\left(\alpha-g\left(x_{0}\right)\right) \exp (-x) .
$$

First, we show that the class $\mathcal{G}(\lambda, \alpha)$ is closed under infima and suprema.
Proposition 3.3. Let $0 \leq \lambda \leq \alpha$. Then every sequence $\left(g_{n}\right)_{n=1}^{\infty} \subset \mathcal{G}(\lambda, \alpha)$ has a subsequence which converges uniformly on compact sets to a function $g \in \mathcal{G}(\lambda, \alpha)$.

In particular, if $g$ is the pointwise infimum or supremum of a family of functions $g_{j} \in \mathcal{G}(\lambda, \alpha)$, then $g \in \mathcal{G}(\lambda, \alpha)$.

Proof. Firstly, the family $\mathcal{G}(\lambda, \alpha)$ is uniformly bounded and uniformly equicontinuous since it is a subset of the set of Lipschitz functions with constant $\alpha-\lambda$ taking values in the interval $[\lambda, \alpha]$. Thus by the Arzelà-Ascoli theorem, $g_{n}$ has a subsequence which converges to a function $g$ uniformly on every compact subset of $\mathbb{R}$.

Next, we show that $g \in \mathcal{G}(\lambda, \alpha)$. It is clear that $g$ takes values in $[\lambda, \alpha]$. Let $x_{0} \in \mathbb{R}, x>0$ and $\varepsilon>0$ be arbitrary. Then for an infinite sequence of $n$, by Lemma 3.2 applied to the function $g_{n}$,

$$
\begin{aligned}
g\left(x_{0}+x\right) & \leq g_{n}\left(x_{0}+x\right)+\varepsilon \\
& \leq \alpha-\left(\alpha-g_{n}\left(x_{0}\right)\right) \exp (-x)+\varepsilon \\
& \leq \alpha-\left(\alpha-g\left(x_{0}\right)\right) \exp (-x)+\varepsilon(1+\exp (-x)) .
\end{aligned}
$$

Since $\varepsilon>0$ was arbitrary,

$$
g\left(x_{0}+x\right) \leq \alpha-\left(\alpha-g\left(x_{0}\right)\right) \exp (-x) .
$$

The lower bound with $\lambda$ in place of $\alpha$ is identical. Thus by Lemma 3.2, $g \in \mathcal{G}(\lambda, \alpha)$.
Now let $\left\{g_{j}: j \in J\right\} \subset \mathcal{G}(\lambda, \alpha)$ be an arbitrary family of functions with supremum $g$. Let $J_{1} \subset J_{2} \subset \cdots \subset J$ be a sequence of finite subsets such that

$$
g=\lim _{n \rightarrow \infty} g_{n} \quad \text { where } \quad g_{n}=\max \left\{g_{j}: j \in J_{n}\right\} .
$$

Since the sequence $g_{n}$ is monotonic, it suffices to verify that $g_{n} \in \mathcal{G}(\lambda, \alpha)$ for each $n \in \mathbb{N}$. To check this, it suffices to check that if $f_{1}, f_{2} \in \mathcal{G}(\lambda, \alpha)$, then $f:=\max \left\{f_{1}, f_{2}\right\} \in \mathcal{G}(\lambda, \alpha)$. Let $x \in \mathbb{R}$ be arbitrary. Since $f_{1}$ and $f_{2}$ are continuous, if $f_{1}(x)<f_{2}(x)$, then $D^{+} f(x)=D^{+} f_{2}(x)$ and $f(x)=f_{2}(x)$. The analogous statement holds if $f_{2}(x)<f_{1}(x)$. Otherwise if $f_{1}(x)=f_{2}(x)$, then $D^{+} f(x)=$ $\max \left\{D^{+} f_{1}(x), D^{+} f_{2}(x)\right\}$. In either case it is clear that $D^{+} f(x) \in[\lambda-f(x), \alpha-f(x)]$, as required.

The case for the infimum of a family of functions is identical.
Next, we show that establishing an approximate form of the inequalities in Lemma 3.2 suffices to show asymptotic equivalence to a function in $\mathcal{G}(\lambda, \alpha)$.

Lemma 3.4. Let $e: \mathbb{R} \rightarrow \mathbb{R}$ be any function with $\lim _{x \rightarrow \infty} e(x)=0$ and let $z \in \mathbb{R}$. Suppose $0 \leq \lambda \leq \alpha$ and let $f: \mathbb{R} \rightarrow \mathbb{R}$ be any function such that for all $x_{0} \geq z$ and $x \geq 0$,

$$
\begin{aligned}
\lambda-\left(\lambda-f\left(x_{0}\right)+e\left(x_{0}\right)\right) \exp (-x) & \leq f\left(x_{0}+x\right) \\
& \leq \alpha-\left(\alpha-f\left(x_{0}\right)\right) \exp (-x)+e\left(x_{0}+x\right)
\end{aligned}
$$

Then there exists $g \in \mathcal{G}(\lambda, \alpha)$ such that $f \sim g$.
Proof. For $y \geq z$, observe that

$$
\lambda(1-\exp (y-z))+(f(z)-e(z)) \exp (y-z) \leq f(y)
$$

and similarly

$$
f(y) \leq \alpha(1-\exp (y-z))+f(z) \exp (y-z)+e(y)
$$

In particular,

$$
\begin{equation*}
\lambda \leq \liminf _{y \rightarrow \infty} f(y) \leq \limsup _{y \rightarrow \infty} f(y) \leq \alpha . \tag{3.1}
\end{equation*}
$$

We first establish the proof in the case $f \geq \lambda$. Let $g$ denote the pointwise maximal element of $\mathcal{G}(\lambda, \alpha)$ satisfying $g \leq f$. Such a function exists by Proposition 3.3. Suppose $x_{0} \in \mathbb{R}$ is arbitrary. For each $0 \leq \delta \leq \alpha-g\left(x_{0}\right)$, let $h_{\delta} \in \mathcal{G}(\lambda, \alpha)$ denote the minimal function satisfying $h_{\delta}\left(x_{0}\right)=g\left(x_{0}\right)+\delta$. Equivalently, let $y_{\delta}$ be chosen so that

$$
\alpha-(\alpha-\lambda) \exp \left(y_{\delta}-x_{0}\right)=g\left(x_{0}\right)+\delta,
$$

and define

$$
h_{\delta}(x):= \begin{cases}\lambda & : x \leq y_{\delta} \\ \alpha-\alpha \exp \left(y_{\delta}-x\right) & : y_{\delta} \leq x \leq x_{0} \\ \lambda-\left(\lambda-\left(g\left(x_{0}\right)+\delta\right)\right) \exp \left(x_{0}-x\right) & : x_{0} \leq x\end{cases}
$$

By minimality, $h_{0} \leq g$. Moreover, by taking $x_{0}$ sufficiently large, we may assume that $y_{\delta} \geq z$ for all $\delta>0$.

If $g\left(x_{0}\right)=\alpha$, then by (3.1), $f\left(x_{0}\right) \leq g\left(x_{0}\right)+e\left(x_{0}\right)$. Otherwise, for $\delta>0$, $g_{\delta}:=\max \left\{h_{\delta}, g\right\} \in \mathcal{G}(\lambda, \alpha)$ and $g_{\delta}\left(x_{0}\right)>g\left(x_{0}\right)$, so by maximality of $g$ there exists $y$ such that

$$
f(y)<h_{\delta}(y)
$$

Since $h_{\delta}(x) \leq f(x)$ for all $x \leq y_{\delta}$, we must have $y \geq z$. If $y \leq x_{0}$ then

$$
\begin{aligned}
f\left(x_{0}\right) & \leq \alpha-(\alpha-f(y)) \exp \left(y-x_{0}\right)+e\left(x_{0}\right) \\
& \leq \alpha-\left(\alpha-h_{\delta}(y)\right) \exp \left(y-x_{0}\right)+e\left(x_{0}\right) \\
& \leq g\left(x_{0}\right)+\delta+e\left(x_{0}\right)
\end{aligned}
$$

and similarly if $y \geq x_{0}$ then

$$
\lambda-\left(\lambda-\left(g\left(x_{0}\right)+\delta\right)\right) \exp \left(x_{0}-y\right) \geq f(y) \geq \lambda-\left(\lambda-f\left(x_{0}\right)+e\left(x_{0}\right)\right) \exp \left(x_{0}-y\right)
$$

so $f\left(x_{0}\right) \leq g\left(x_{0}\right)+e\left(x_{0}\right)+\delta$. Since $\delta>0$ was arbitrary, it follows that if $g\left(x_{0}\right)<\alpha$ then

$$
f\left(x_{0}\right) \leq g\left(x_{0}\right)+e\left(x_{0}\right)
$$

Of course, we can also apply the trivial bound $f\left(x_{0}\right) \leq \alpha+e\left(x_{0}\right)$. From this it follows that $\lim _{x \rightarrow \infty}(f(x)-g(x))=0$.

To establish the general case, one can apply the above strategy to the function $\max \{f, \lambda\}$, and the lower bound also follows by (3.1).

We can now prove Proposition 1.5 and show that the covering class is well-defined. In fact, we can prove a slightly improved bound using the so-called quasi-Assouad dimension of $E$ [LX16], which is defined as follows:

$$
\begin{gathered}
\operatorname{dim}_{\mathrm{qA}} E=\lim _{\theta \rightarrow 1^{-}} \inf \left\{t \geq 0:(\exists C>0)\left(\forall 0<r \leq R^{1 / \theta} \leq R<1\right)(\forall x \in E)\right. \\
\left.N_{r}(E \cap B(x, R)) \leq C\left(\frac{R}{r}\right)^{t}\right\} .
\end{gathered}
$$

If $E \subset X$ where $X$ is Ahlfors-David $\alpha$-regular, then $\operatorname{dim}_{\mathrm{qA}} E \leq \alpha$. In particular, if $E \subset \mathbb{R}^{d}$, then $0 \leq \operatorname{dim}_{\mathrm{qA}} E \leq d$. More detail on the quasi-Assouad dimension, and related Assouad-type dimensions, can be found in [Fra20].
Proposition 3.5. Let $E \subset \mathbb{R}^{d}$ be non-empty and bounded with associated function $f: \mathbb{R} \rightarrow \mathbb{R}$ defined by

$$
f(x)=s_{E}(\exp (-\exp (x)))
$$

Then there exists $g \in \mathcal{G}\left(0, \operatorname{dim}_{\mathrm{qA}} E\right) \subset \mathcal{G}(0, d)$ such that $f \sim g$.
Proof. Write $\alpha=\operatorname{dim}_{\mathrm{qA}} E$ and set $\alpha_{n}=\alpha+1 / n$. By the definition of quasiAssouad dimension, for each $n \in \mathbb{N}$, get a constant $C_{n}$ so that for all $x \in E$ and $0<r \leq R^{(n+1) / n} \leq R<1$,

$$
N_{r}(E \cap B(x, R)) \leq C\left(\frac{R}{r}\right)^{\alpha_{n}}
$$

Rearranging this bound, we obtain for $x_{0} \in \mathbb{R}$ and $x \geq \log \left(\frac{n+1}{n}\right)$,

$$
\begin{aligned}
f\left(x_{0}+x\right) & \leq \alpha_{n}-\left(\alpha_{n}-f\left(x_{0}\right)\right) \exp (-x)+C_{n} \exp \left(-x_{0}-x\right) \\
& =\alpha-\left(\alpha-f\left(x_{0}\right)\right) \exp (-x)+C_{n} \exp \left(-x_{0}-x\right)+\frac{1}{n} .
\end{aligned}
$$

Of course, we also have the bounds from the ambient Euclidean space as guaranteed by Lemma 2.2: for all $x_{0} \in \mathbb{R}$ and $x \geq 0$,

$$
f\left(x_{0}\right) \exp (-x) \leq f\left(x_{0}+x\right) \leq d-\left(d-f\left(x_{0}\right)\right) \exp (-x)+A_{d} \exp \left(-x_{0}-x\right)
$$

The upper bound further implies that for $0 \leq x \leq \log \left(\frac{n+1}{n}\right)$,

$$
f\left(x_{0}+x\right) \leq \alpha-\left(\alpha-f\left(x_{0}\right)\right) \exp (-x)+A_{d} \exp \left(-x_{0}-x\right)+\frac{d-\alpha}{n+1}
$$

Thus for $y \in \mathbb{R}$, set

$$
e(y):=\inf _{n \in \mathbb{N}} \max \left\{A_{d} \exp (-y)+\frac{d-\alpha}{n+1}, C_{n} \exp (-y)+\frac{1}{n}\right\} .
$$

Of course, $\lim _{y \rightarrow \infty} e(y)=0$. Moreover, for all $x_{0} \in \mathbb{R}$ and $x \geq 0$,

$$
f\left(x_{0}+x\right) \leq \alpha-\left(\alpha-f\left(x_{0}\right)\right) \exp (-x)+e\left(-x_{0}-x\right)
$$

Thus the result follows by Lemma 3.4.
3.3. An alternative asymptotic formula. Finally, we can prove Theorem E. In fact, it is a direct consequence of the following proposition combined with Theorem C.

Proposition 3.6. Let $0 \leq \lambda \leq \alpha$ be arbitrary and let $f \in \mathcal{G}(0, \alpha)$. Let

$$
g(x)=\sup _{\theta \in(0,1]}((1-\theta) \lambda+\theta f(x-\log (1 / \theta))) .
$$

Then $f$ is the pointwise minimal element of $\mathcal{G}(\lambda, \alpha)$ bounded below by $g$.
Moreover, if $D^{+} g(x) \neq \lambda-g(x)$, then $g(x)=f(x)$ and $D^{+} g(x)=D^{+} f(x)$.
Proof. First, suppose $g_{0} \in \mathcal{G}(\lambda, \alpha)$. Let $x_{0} \in \mathbb{R}$ be fixed, and let $\varepsilon>0$. By the definition of $g$, get $0<\theta_{0} \leq 1$ such that

$$
\begin{equation*}
\left(1-\theta_{0}\right) \lambda+\theta_{0} f\left(x_{0}-\log \left(1 / \theta_{0}\right)\right) \geq g\left(x_{0}\right)-\varepsilon . \tag{3.2}
\end{equation*}
$$

Then since $f_{0} \in \mathcal{G}(\lambda, \alpha)$ and $f \leq f_{0}$,

$$
\begin{aligned}
f_{0}\left(x_{0}\right) & \geq \lambda-\left(\lambda-f_{0}\left(x_{0}-\log \left(1 / \theta_{0}\right)\right) \theta_{0}\right) \\
& \geq\left(1-\theta_{0}\right) \lambda+\theta_{0} f\left(x_{0}-\log \left(1 / \theta_{0}\right)\right) \\
& \geq g\left(x_{0}\right)-\varepsilon .
\end{aligned}
$$

Since $x_{0} \in \mathbb{R}$ and $\varepsilon>0$ were arbitrary, it follows that $f_{0} \geq f$.

In the remainder of the proof, we show that $h \in \mathcal{G}(\lambda, \alpha)$. Let $x_{0} \in \mathbb{R}, x>0$, and $\varepsilon>0$ be arbitrary. Again by the definition of $g$, get $0<\theta_{0} \leq 1$ so that (3.2) holds and let $\theta=\exp (-x)$. Then

$$
\begin{aligned}
g\left(x_{0}+x\right) & \geq\left(1-\theta \theta_{0}\right) \lambda+\theta \theta_{0} f\left(x_{0}+x-\log \left(1 /\left(\theta \theta_{0}\right)\right)\right) \\
& =(1-\theta) \lambda+\theta\left(\left(1-\theta_{0}\right) \lambda+\theta_{0} f\left(x_{0}-\log (1 / \theta)\right)\right) \\
& \geq(1-\theta) \lambda+\theta\left(g\left(x_{0}\right)-\varepsilon\right) \\
& \geq \lambda-\left(\lambda-g\left(x_{0}\right)\right) \exp (-x)-\varepsilon .
\end{aligned}
$$

This gives the first inequality in Lemma 3.2, and also implies that $D^{+} g(x) \geq \lambda-g(x)$ for all $x \in \mathbb{R}$.

To complete the proof, we establish the following stronger fact: if $D^{+} g(x)>$ $\lambda-g(x)$, then $g(x)=f(x)$ and $D^{+} g(x)=D^{+} f(x)$. Suppose $x \in \mathbb{R}$ is such that $D^{+} g(x)>\lambda-g(x)$. Equivalently, there exists $\kappa>\lambda$ and a sequence $\left(x_{n}\right)_{n=1}^{\infty}$ converging to $x$ from the right and $\kappa_{n}$ converging to $\kappa$ so that

$$
\begin{equation*}
g\left(x_{n}\right)=\kappa_{n}-\left(\kappa_{n}-g(x)\right) \exp \left(x-x_{n}\right) . \tag{3.3}
\end{equation*}
$$

Now, suppose $y \leq x$ is arbitrary and let $\kappa>\kappa^{\prime}>\lambda$. We may assume that $\kappa_{n} \geq \kappa^{\prime}$ for all $n$. As proven above,

$$
g(x) \geq \lambda-(\lambda-g(y)) \exp (y-x)
$$

Combining the previous equations,

$$
\begin{aligned}
g\left(x_{n}\right) & \geq \kappa^{\prime}-\left(\kappa^{\prime}-(\lambda-(\lambda-g(y)) \exp (y-x))\right) \exp \left(x-x_{n}\right) \\
& \geq\left(1-\exp \left(y-x_{n}\right)\right) \lambda+g(y) \exp \left(y-x_{n}\right)+\delta,
\end{aligned}
$$

where

$$
\delta:=\left(1-\exp \left(x-x_{n}\right)\right)\left(\kappa^{\prime}-\lambda\right)>0
$$

is a constant which does not depend on $y$. In particular, for each $x_{n}$ there exists $\theta_{n}$ such that $y_{n}=x_{n}-\log \left(1 / \theta_{n}\right) \geq x$ and

$$
\begin{equation*}
g\left(x_{n}\right)=\left(1-\theta_{n}\right) \lambda+\theta_{n} f\left(y_{n}\right) . \tag{3.4}
\end{equation*}
$$

Since $x_{n}$ converges to $x, \theta_{n}$ converges to 1 so by continuity of $f, g(x)=f(x)$. Finally, since $g(x)=f(x)$ and $f \geq g$, it remains to show that $D^{+} g(x) \leq D^{+} f(x)$. To see this, again combining (3.3) and (3.4), for each $n$,

$$
f\left(y_{n}\right) \geq \kappa_{n}-\left(\kappa_{n}-f(x)\right) \exp \left(x-y_{n}\right)
$$

But $\kappa_{n}$ converges to $\kappa$ and $y_{n}$ converges to $x$, so $D^{+} f(x) \geq D^{+} g(x)$ as claimed.
Remark 3.7. Note that if $D^{+} f(x)>\lambda-f(x)$, this does not imply that $f(x)=g(x)$. For a visual depiction of this fact, see Figure 1.

## 4. EXAMPLES AND APPLICATIONS

4.1. Constructing countable discrete sets. In this section, we will demonstrate the existence of countable discrete sets with various approximation properties. To do so, we will use homogeneous Moran sets. The construction of such sets is analogous to the usual $2^{d}$-corner Cantor set, except that the subdivision ratios need not be the same at each level.

Set $\mathcal{J}=\{0,1\}^{d}$. We write $\mathcal{J}^{*}=\bigcup_{n=0}^{\infty} \mathcal{J}^{n}$, and we denote the word of length 0 by $\varnothing$. Suppose we have a sequence $\boldsymbol{r}=\left(r_{n}\right)_{n=1}^{\infty}$ with $0<r_{n} \leq 1 / 2$ for each $n \in \mathbb{N}$. Then for all $n$ and $i \in \mathcal{J}$, we define $S_{i}^{n}: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}$ by

$$
S_{i}^{n}(x):=r_{n} x+b_{i}^{n}
$$

where $b_{i}^{n} \in \mathbb{R}^{d}$ is given by

$$
\left(b_{\boldsymbol{i}}^{n}\right)^{(j)}=\left\{\begin{array}{ll}
0 & : \boldsymbol{i}^{(j)}=0 \\
1-r_{n} & : \boldsymbol{i}^{(j)}=1
\end{array} .\right.
$$

We then set

$$
M_{n}=\bigcup_{\left(i_{1}, \ldots, i_{n}\right) \in \mathcal{J}^{n}} S_{i_{1}}^{1} \circ \cdots \circ S_{i_{n}}^{n}\left([0,1]^{d}\right) \quad \text { and } \quad M=M(\boldsymbol{r}):=\bigcap_{n=1}^{\infty} M_{n}
$$

We call $M$ a homogeneous Moran set. Note that $M_{n}$ consists of $2^{d n}$ hypercubes, each with side-length $\rho_{n}:=r_{1} \cdots r_{n}$.

We first demonstrate the existence of homogeneous Moran sets with arbitrary covering class.

Lemma 4.1. Let $d \in \mathbb{N}$ and $g \in \mathcal{G}(0, d)$ be arbitrary. Then there exists a homogeneous Moran set with covering class $g$.

Proof. First assume that $g \nsim 0$, and note that ${\lim \sup _{x \rightarrow \infty} g(x)>0 \text {. Therefore for }}^{2}$ all $y \in \mathbb{R}$ there exists a minimal $\psi(y)>y$ so that

$$
g(y) \exp (y-\psi(y))=g(\psi(y))-d \log (2) \cdot \exp (-\psi(y))
$$

Now set $x_{1}=0$ and, inductively, set $x_{k+1}=\psi\left(x_{k}\right)$ for each $k \in \mathbb{N}$. Let $\rho_{k}=$ $\exp \left(-\exp \left(x_{k}\right)\right)$ denote the corresponding scales (note that $\rho_{1}=r_{1}$ ), and set $r_{k}:=$ $\rho_{k} / \rho_{k-1}$ for $k \geq 2$. Thus for $0<\delta \leq r_{1}$, if $k$ is such that $\rho_{k}<\delta \leq \rho_{k-1}$, we set

$$
\bar{s}(\delta)=\frac{k d \log 2}{\log (1 / \delta)}
$$

The exact same calculation as in the proof of [BR22, Lemma 3.4] gives that for all $k \geq 2$ we have $r_{k} \in(0,1 / 2], \bar{s}\left(\rho_{k}\right)=g\left(x_{k}\right)$, and

$$
\begin{equation*}
g(x)-d \log (2) \exp (-x) \leq \bar{s}(\exp (-\exp (x))) \leq g(x) \tag{4.1}
\end{equation*}
$$

for all $x \geq x_{2}$. In particular, the resulting homogeneous Moran set has covering class $g$.

Finally, if $g \sim 0$, then it is straightforward to check directly that the homogeneous Moran set given by sequence $r_{j}=2^{-2^{j}}$ has covering class $g$.

Now by discretising a homogeneous Moran set, we can obtain a countable discrete set with arbitrary covering class.

Lemma 4.2. Let $d \in \mathbb{N}$ and $g \in \mathcal{G}(0, d)$ be arbitrary. Then there exists a countable discrete set $F \subset(0,1)^{d}$ which accumulates only at 0 and has covering class $g$.

Proof. By Lemma 4.1, get a homogeneous Moran set $M$ with covering class $g$. For all $n \in \mathbb{N}$ let $F_{n}$ be a finite subset of $M \cap(0,1 / n)^{d}$ whose Hausdorff distance from $M \cap[0,1 / n]^{d}$ is at most $2^{-n}$. Then

$$
F:=\bigcup_{n=1}^{\infty} F_{n} .
$$

is clearly discrete and accumulates only at 0 . If $2^{-n} \leq r<2^{-(n-1)}$, then

$$
N_{r}(F) \geq N_{r}\left(F_{n}\right) \approx N_{r}\left(M \cap[0,1 / n]^{d}\right) \approx n^{-d} N_{r}(M)
$$

with implicit constants independent of $n$. In particular, as $x \rightarrow \infty$,

$$
\left|s_{F}(\exp (-\exp (x)))-s_{M}(\exp (-\exp (x)))\right| \lesssim x e^{-x}
$$

Therefore since $M$ has covering class $g, F$ also does.
Finally, we modify the countable discrete set provided by Lemma 4.2 to obtain an infinitely generated self-similar IFS with specified Hausdorff dimension and fixed points having arbitrary covering class.

Lemma 4.3. Let $d \in \mathbb{N}$. Let $g \in \mathcal{G}(0, d)$ and $0<h<d$ be arbitrary. Then there exists a countable self-similar IFS $\left\{S_{i}\right\}_{i \in \mathcal{I}}$ with fixed points $F$ and attractor $\Lambda$ such that $F$ has covering class $g$ and $\operatorname{dim}_{H} \Lambda=h$.

Proof. Since $h<d$, we may fix $n$ large enough that

$$
\begin{equation*}
\frac{\log \left(2^{d n}-1\right)}{n \log 2}>h \tag{4.2}
\end{equation*}
$$

By Lemma 4.2 , let $F_{0} \subset(0,1)^{d}$ be a countable discrete set which accumulates only at 0 and has covering class $g$, and let $F_{1}:=F_{0} \cap\left(0,2^{-n}\right)^{d}$. To each $p \in F_{1}$ we will now choose a similarity map $S_{p}$ which fixes $p$ and has some contraction ratio $c_{p} \in(0,1)$. We choose the contraction ratios to be small enough that $S_{p}\left([0,1]^{d}\right) \subset\left(0,2^{-n}\right)^{d}$ for all $p \in F_{1}$, and $S_{p}\left([0,1]^{d}\right) \cap S_{q}\left([0,1]^{d}\right)=\varnothing$ whenever $p, q \in F_{1}$ are distinct, and moreover $\sum_{p \in F_{1}} c_{p}^{h}<1$. By (4.2) there exists $c \in\left(0,2^{-n}\right)$ such that

$$
\begin{equation*}
\left(2^{d n}-1\right) c^{h}=1-\sum_{p \in F_{1}} c_{p}^{h} \tag{4.3}
\end{equation*}
$$



Figure 2. A plot of the covering class of $F$ (dashed) and the covering class of $\Lambda$ (solid) corresponding to the concatenation of $\left(g_{1, n}, g_{2, n}\right)$ and $\left(f_{1, n}, f_{2, n}, f_{3, n}\right)$ respectively. In this plot, we assume that $h<s<\beta<t$ to remove the dependence on $n$.

Fix similarity maps $S_{1}, \ldots, S_{2^{\text {nd }}-1}$, each with contraction ratio $c$, such that whenever $1 \leq i<j \leq 2^{\text {nd }}-1$, we have that $S_{i}\left([0,1]^{d}\right)$ and $S_{j}\left([0,1]^{d}\right)$ are pairwise-disjoint subsets of $(0,1)^{d} \backslash\left(0,2^{-n}\right]^{d}$.

Now consider the countable self-similar IFS

$$
\left\{S_{p}: p \in F_{1}\right\} \cup\left\{T_{i}\right\}_{1 \leq i \leq 2^{n d}-1} .
$$

Since $F_{0}$ accumulates only at 0 , the symmetric difference of $F_{0}$ and the set $F$ of fixed points of this CIFS is finite. Therefore since $F_{0}$ has covering class $g$, the same is true for $F$. Moreover, combining (1.3) due to Mauldin \& Urbański with (4.3), the Hausdorff dimension of the limit set equals $h$.

Finally, using the construction established above, we prove Theorem D. For convenience of notation, we make one more definition.
Definition 4.4. Given a sequence of functions $\left(f_{k}\right)_{k=1}^{\infty}$ each defined on some inter$\operatorname{val}\left[0, a_{k}\right]$, the concatenation of $\left(f_{k}\right)_{k=1}^{\infty}$ is the function $f:\left(-\infty, \sum_{k=1}^{\infty} a_{k}\right) \rightarrow \mathbb{R}$ given as follows: for each $x>0$ with $\sum_{j=0}^{k-1} a_{j}<x \leq \sum_{j=0}^{k} a_{j}$ where $a_{0}=0$ we define

$$
f(x)=f_{k}\left(x-\sum_{j=0}^{k-1} a_{j}\right)
$$

and for $x \leq 0$ we define $f(x)=f_{1}(0)$.
Proof (of Theorem D). Recall that the bounds on $\underline{\operatorname{dim}}_{\mathrm{B}} \Lambda$ were originally proven in Corollary 3.1; what remains is to verify sharpness.

We first observe that the result is straightforward to prove if $\mathcal{D}(h, s, t, d)$ is a singleton. If this is the case, let $g \in \mathcal{G}(0, d)$ be such that $\liminf _{x \rightarrow \infty} g(x)=s$ and $\limsup _{x \rightarrow \infty} g(x)=t$. Applying Lemma 4.3, get a self-similar IFS $\left\{S_{i}\right\}_{i \in \mathcal{I}}$ with fixed points $F$ and attractor $\Lambda$ such that $F$ has covering class $g$. Then by Corollary 3.1, since $\mathcal{D}(h, s, t, d)$ is a singleton, it must be that $\operatorname{dim}_{B} \Lambda$ is the expected value.

Otherwise, $\mathcal{D}(h, s, t, d)$ is not a singleton so that $0<h<t$ and $0<s<t$. Let $\beta \in \mathcal{D}(h, s, t, d)$, or equivalently

$$
\begin{equation*}
\max \{s, h\} \leq \beta \leq h+\frac{(t-h)(\alpha-h) s}{\alpha \cdot t-h \cdot s} \tag{4.4}
\end{equation*}
$$

Given $\delta>0$, set

$$
\beta_{n}:=\max \left\{\beta, h+\frac{\delta}{n}\right\} \quad \text { and } \quad t_{n}:=\min \left\{t, d-\frac{\delta}{n}\right\} .
$$

Note that since $t>\max \{h, s\}$, it follows that $h \leq \beta<t$ so by taking $\delta>0$ sufficiently small, we may assume that

$$
\begin{equation*}
h<\beta_{n}<t_{n}<d \quad \text { and } \quad \beta_{n} \leq h+\frac{(t-h)(\alpha-h) s}{\alpha \cdot t-h \cdot s} . \tag{4.5}
\end{equation*}
$$

(Of course, these choices are only actually necessary in the case that $\beta=h$ or $t=d$; otherwise, we could just take $\beta_{n}=\beta$ and $t_{n}=t$ for all $n \in \mathbb{N}$.)

We now choose some constants. Let $a_{1, n}$ be chosen so that $t_{n} \exp \left(-a_{1, n}\right)=s$ and let $a_{3, n}$ be chosen so that $d-(d-s) \exp \left(-a_{3, n}\right)=t_{n+1}$. Then let $a_{3, n}^{\prime} \leq a_{3, n}$ be chosen so that $d-(d-s) \exp \left(-a_{3, n}^{\prime}\right)=\beta_{n}$. Finally, let $a_{2, n} \geq 0$ be chosen so that

$$
h^{\prime}-\left(h^{\prime}-t_{n}\right) \exp \left(-a_{1, n}-a_{2, n}-a_{3, n}^{\prime}\right)=\beta_{n} .
$$

Note that $a_{2, n} \geq 0$ precisely by the second equation in (4.5).
Now, we define functions

- $f_{1, n}(x)=t_{n} \exp (-x)$ for $x \in\left[0, a_{1, n}\right]$;
- $f_{2, n}(x)=s$ for $x \in\left[0, a_{2, n}\right]$; and
- $f_{3, n}(x)=d-(d-s) \exp (-x)$ for $x \in\left[0, a_{3, n}\right]$.

Finally, let $f$ be the concatenation of the sequence of functions

$$
\left(f_{1,1}, f_{2,1}, f_{3,1}, f_{1,2}, f_{2,2}, f_{3,2}, f_{1,3}, \ldots\right)
$$

Of course, $f \in \mathcal{G}(0, d)$ and moreover by construction $\liminf _{x \rightarrow \infty} f(x)=s$ and $\limsup _{x \rightarrow \infty} f(x)=\lim _{n \rightarrow \infty} t_{n}=t$. Moreover, the minimal function $g \in \mathcal{G}(h, d)$ satisfying $f \leq g$ is similarly the concatenation of the sequence of functions

$$
\left(g_{1,1}, g_{2,1}, g_{1,2}, g_{2,2}, g_{1,3}, \ldots\right)
$$

where, setting $b_{1, n}=a_{1, n}+a_{2, n}+a_{3, n}^{\prime}$ and $b_{2, n}=a_{3, n}-a_{3, n}^{\prime}$,

- $g_{1, n}(x)=h-\left(h-t_{n}\right) \exp (x)$ for $x \in\left[0, b_{1, n}\right]$; and
- $g_{2}(x)=\left(d-\left(d-\beta_{n}\right) \exp (-x)\right.$ for $x \in\left[0, b_{2, n}\right]$.

A depiction of the functions $f$ and $g$ can be found in Figure 2.
To conclude the proof, by Lemma 4.3, get a self-similar IFS $\left\{S_{i}\right\}_{i \in \mathcal{I}}$ with fixed points $F$ and attractor $\Lambda$ such that $F$ has covering class $g$ and $\operatorname{dim}_{H} \Lambda=h$. Then recalling Theorem E,

$$
\underline{\operatorname{dim}}_{\mathrm{B}} \Lambda=\liminf _{x \rightarrow \infty} g(x)=\lim _{n \rightarrow \infty} \beta_{n}=\beta
$$

as required.
4.2. Continued fraction expansions with restricted entries. In this section we prove Theorem A. For a non-empty, proper subset $I \subset \mathbb{N}$, define

$$
\Lambda_{I}:=\left\{z \in(0,1) \backslash \mathbb{Q}: z=\frac{1}{b_{1}+\frac{1}{b_{2}+\frac{1}{\ddots}}}, b_{n} \in I \text { for all } n \in \mathbb{N}\right\}
$$

It is well-known (see, for instance, [MU99, p. 4997]) that $\Lambda_{I}$ is the limit set of the CIFS given by the inverse branches of the Gauss map corresponding to the elements of $I$. Indeed, this is one of the motivations for working with countable IFSs given by conformal maps rather than just similarity maps.

Lemma 4.5. Working in $\mathbb{R}$, letting $X:=[0,1]$,

- If $1 \notin I$ then $\left\{S_{b}(x):=1 /(b+x): b \in I\right\}$ is a CIFS with limit set $\Lambda_{I}$.
- If $1 \in I$ then $\left\{S_{b}(x):=1 /(b+x): b \in I, b \neq 1\right\} \cup\left\{S_{1 b}(x):=\frac{1}{b+\frac{1}{1+x}}: b \in I\right\}$ is $a$ CIFS with limit set $\Lambda_{I}$.

We can finally prove our headline result. In fact, since continued fraction sets $\Lambda_{I}$ are Borel and invariant for the Gauss map, the following stronger result immediately implies Theorem A.

Theorem 4.6. For all $0<a<1$ there exists an infinite proper subset $I \subset \mathbb{N}$ such that the box dimension of the continued fraction set $\Lambda_{I}$ does not exist, and $\Lambda_{I} \subset(0, a)$.

Proof. We define a sequence $\left(a_{n}\right)_{n \geq 0}$ inductively by setting $a_{0}=2$ and $a_{n}=$ $\left(2 a_{n-1}\right)^{n}$ for $n \geq 1$. Then let

$$
I_{0}=\left\{b^{2}: b \in \mathbb{N} \cap \bigcup_{n=0}^{\infty}\left[a_{n}, 2 a_{n}\right]\right\} .
$$

Now, using notation from Lemma 4.5, we have $\left|S_{b}^{\prime}(x)\right| \approx b^{-2}$ uniformly for $b \geq 2$ and $x \in[0,1]$. Therefore

$$
P(t)<\infty \quad \text { for all } \quad t>1 / 4
$$

In particular, by [MU96, Theorem 3.23] there exists $N \in \mathbb{N}$ large enough that if

$$
I:=I_{0} \cap[N, \infty)
$$

then $\operatorname{dim}_{H} \Lambda_{I}<1 / 3$. We may increase $N$ further if necessary so that $\Lambda_{I} \subset(0, a)$.
Now, note that the orbit set $Q_{I}:=\mathcal{O}(0,1)=\left\{1 / b: b \in I_{0}\right\}$ is a discrete approximation of the CIFS $\left\{S_{b}: b \in I_{0}\right\}$. Let $F_{I}$ be the set of fixed points and let $\Lambda_{I}$ be the limit set. A mean value theorem argument gives that $(n+1)^{-2}-n^{-2} \approx n^{-3}$. Therefore using Lemma 2.5,

$$
N_{\left(2 a_{n}\right)^{-3}}\left(F_{I}\right) \approx N_{\left(2 a_{n}\right)^{-3}}\left(Q_{I}\right) \geq N_{\left(2 a_{n}\right)^{-3}}\left(\left\{b^{-2}: a_{n} \leq b \leq 2 a_{n}\right\}\right) \gtrsim a_{n} .
$$

In particular, $\overline{\operatorname{dim}}_{\mathrm{B}} F_{i} \geq 1 / 3$. On the other hand, for $n \geq 1$,

$$
N_{a_{n}^{-2}}\left(F_{I}\right) \approx N_{a_{n}^{-2}}\left(Q_{I}\right) \leq 2+a_{n-1} \lesssim a_{n}^{1 / n} .
$$

This implies that $\operatorname{dim}_{\mathrm{B}} F_{I} \leq 1 / n$ for all $n$, so $\operatorname{dim}_{\mathrm{B}} F_{I}=0$. In particular,

$$
\max \left\{\operatorname{dim}_{\mathrm{H}} \Lambda_{I}, \underline{\operatorname{dim}}_{\mathrm{B}} F_{I}\right\}=\operatorname{dim}_{\mathrm{H}} \Lambda_{I}<1 / 3 \leq \operatorname{dim}_{\mathrm{B}} F_{I} .
$$

Thus by Theorem B, the box dimension of $\Lambda_{I}$ does not exist.

## ACKNOWLEDGEMENTS

We thank Jonathan Fraser for several discussions related to the contents of this paper. We thank Simon Baker for comments on a draft version of this manuscript and Thomas Jordan for suggesting some relevant references. AB was supported by an EPSRC New Investigators Award (EP/W003880/1). AR was supported by EPSRC Grant EP/V520123/1 and the Natural Sciences and Engineering Research Council of Canada.

## References

[BF23] A. Banaji and J. M. Fraser. Intermediate dimensions of infinitely generated attractors. Trans. Amer. Math. Soc. 376 (2023), 2449-2479. z.bl:07662347.
[BF24] A. Banaji and J. M. Fraser. Assouad type dimensions of infinitely generated self-conformal sets. Nonlinearity 37 (2024), Paper No. 045004, 32pp. zbl:07844477.
[BR22] A. Banaji and A. Rutar. Attainable forms of intermediate dimensions. Ann. Fenn. Math. 47 (2022), 939-960. zbl:1509. 28005.
[BHR19] B. Bárány, M. Hochman, and A. Rapaport. Hausdorff dimension of planar self-affine sets and measures. Invent. Math. 216 (2019), 601-659. zbl:1414.28014.
[Bar08] L. Barreira. Dimension and recurrence in hyperbolic dynamics. Vol. 272. Basel: Birkhäuser, 2008. zbl:1161.37001.
[BG11] L. Barreira and K. Gelfert. Dimension estimates in smooth dynamics: a survey of recent results. Ergodic Theory Dynam. Systems 31 (2011), 641-671. zbl:1230.37032.
[Bar96] L. M. Barreira. A non-additive thermodynamic formalism and applications to dimension theory of hyperbolic dynamical systems. Ergodic Theory Dynam. Systems 16 (1996), 871-927. zbl: 0862.58042.
[Bed84] T. Bedford. Crinkly curves, Markov partitions and box dimensions. PhD thesis. University of Warwick, 1984.
[Bow79] R. Bowen. Hausdorff dimension of quasi-circles. Publ. Math., Inst. Hautes Étud. Sci. 50 (1979), 11-25. zbl:0439. 30032.
[CPZ19] Y. Cao, Y. Pesin, and Y. Zhao. Dimension estimates for non-conformal repellers and continuity of sub-additive topological pressure. Geom. Funct. Anal. 29 (2019), 1325-1368. zbl:1427.37018.
[CLU20] V. Chousionis, D. Leykekhman, and M. Urbański. On the dimension spectrum of infinite subsystems of continued fractions. Trans. Amer. Math. Soc. 373 (2020), 1009-1042. z.bl:1437. 37032.
[DS17] T. Das and D. Simmons. The Hausdorff and dynamical dimensions of self-affine sponges: a dimension gap result. Invent. Math. 210 (2017), 85-134. zbl:1387.37026.
[Fa189] K. J. Falconer. Dimensions and measures of quasi self-similar sets. Proc. Amer. Math. Soc. 106 (1989), 543-554. zbl: 0683.58034.
[Fa188] K. J. Falconer. The Hausdorff dimension of self-affine fractals. Math. Proc. Cambridge Philos. Soc. 103 (1988), 339-350. zbI: 0642.28005.
[Fal14] K. J. Falconer. Fractal geometry. Mathematical foundations and applications. Hoboken, NJ: John Wiley \& Sons, 2014. zbl:1285.28011.
[Fra12] J. M. Fraser. Inhomogeneous self-similar sets and box dimensions. Studia Math. 213 (2012), 133-156. zbl:1342. 28013.
[Fra20] J. M. Fraser. Assouad dimension and fractal geometry. Vol. 222. Cambridge: Cambridge University Press, 2020. zbl:1467. 28001.
[GP97] D. Gatzouras and Y. Peres. Invariant measures of full dimension for some expanding maps. Ergodic Theory Dynam. Systems 17 (1997), 147-167. zbl:0876.58039.
$[G K K+24+] \quad$ S. van Golden, C. Kalle, S. Kombrink, and T. Samuel. Dimensions of infinitely generated self-affine sets and restricted digit sets for signed Lüroth expansions. Preprint. arxiv:2404.10749.
[Jur23] N. Jurga. Nonexistence of the box dimension for dynamically invariant sets. Anal. PDE 16 (2023), 2385-2399. zbl: 1531.37017.
[KM24+] A. Käenmäki and I. D. Morris. Thermodynamic formalism of countably generated self-affine sets. Preprint. arxiv:2405.00520.
[KR14] A. Käenmäki and H. W. J. Reeve. Multifractal analysis of Birkhoff averages for typical infinitely generated self-affine sets. J. Fractal Geom. 1 (2014), 83-152. zbl:1292.28016.
[LX16] F. Lü and L.-F. Xi. Quasi-Assouad dimension of fractals. J. Fractal Geom. 3 (2016), 187-215. zbl:1345. 28019.
[MU02] R. D. Mauldin and M. Urbanski. Fractal measures for parabolic IFS. Adv. Math. 168 (2002), 225-253. zbl:1013. 28007.
[MU96] R. D. Mauldin and M. Urbański. Dimensions and measures in infinite iterated function systems. Proc. Lond. Math. Soc. 73 (1996), 105-154. zbl:0852.28005.
[MU99] R. D. Mauldin and M. Urbański. Conformal iterated function systems with applications to the geometry of continued fractions. Trans. Amer. Math. Soc. 351 (1999), 4995-5025. zbl:0940. 28009.
[MU00] R. D. Mauldin and M. Urbański. Parabolic iterated function systems. Ergodic Theory Dynam. Systems 20 (2000), 1423-1447. zbl:0982. 37045.
[MU22] V. Mayer and M. Urbański. The exact value of Hausdorff dimension of escaping sets of class $\mathcal{B}$ meromorphic functions. Geom. Funct. Anal. 32 (2022), 53-80. zbl:1500.37035.
[McM84] C. McMullen. The Hausdorff dimension of general Sierpiński carpets. Nagoya Math. J. 96 (1984), 1-9. zbl: 0539.28003.
[Pes98] Y. B. Pesin. Dimension theory in dynamical systems. Chicago: The University of Chicago Press, 1998. zbl:0895.58033.
[PU21] M. Pollicott and M. Urbanski. Asymptotic counting in conformal dynamical systems. Vol. 1327. 1327. Providence, RI: American Mathematical Society (AMS), 2021. zbl:1482.37002.
[Rue82] D. Ruelle. Repellers for real analytic maps. Ergodic Theory Dynam. Systems 2 (1982), 99-107. zbl:0506.58024.
[Sch01] J. Schmeling. Dimension theory of smooth dynamical systems. In: "Ergodic theory, analysis, and efficient simulation of dynamical systems". Berlin: Springer, 2001, 109-129. zbl:1001. 37018.
[SW15] S. Seuret and B.-W. Wang. Quantitative recurrence properties in conformal iterated function systems. Adv. Math. 280 (2015), 472-505. zbl:1319.11050.
[Sta01] G. M. Stallard. Dimensions of Julia sets of hyperbolic meromorphic functions. Bull. Lond. Math. Soc. 33 (2001), 689-694. zbl:1034. 30019.
[Sta04] G. M. Stallard. Dimensions of Julia sets of hyperbolic entire functions. Bull. Lond. Math. Soc. 36 (2004), 263-270. zbl:1050. 30017.
[WW08] B. Wang and J. Wu. Hausdorff dimension of certain sets arising in continued fraction expansions. Adv. Math. 218 (2008), 1319-1339. $\mathrm{zbl}: 1233.11084$.

Amlan Banaji<br>Mathematical Sciences, Loughborough University, Loughborough, LE11 3TU, United Kingdom<br>Email: A.F.Banaji@lboro.ac.uk<br>\section*{Alex Rutar}<br>University of St Andrews, Mathematical Institute, St Andrews, KY16 9SS, Scotland<br>Email: alex@rutar.org

